

TRANSPORTING MICROSTRUCTURE AND DISSIPATIVE EULER FLOWS

TRISTAN BUCKMASTER, CAMILLO DE LELLIS,
AND LÁSZLÓ SZÉKELYHIDI JR.

ABSTRACT. Recently the second and third author developed an iterative scheme for obtaining rough solutions of the 3D incompressible Euler equations in Hölder spaces (*arXiv:1202.1751* and *arXiv:1205.3626* (2012)). The motivation comes from Onsager's conjecture. The construction involves a superposition of weakly interacting perturbed Beltrami flows on infinitely many scales. An obstruction to better regularity arises from the errors in the linear transport of a fast periodic flow by a slow velocity field.

In a recent paper P. Isett (*arXiv:1211.4065*) has improved upon our methods, introducing some novel ideas on how to deal with this obstruction, thereby reaching a better Hölder exponent - albeit below the one conjectured by Onsager. In this paper we give a shorter proof of Isett's final result, adhering more to the original scheme and introducing some new devices. More precisely we show that for any positive ε there exist periodic solutions of the 3D incompressible Euler equations which dissipate the total kinetic energy and belong to the Hölder class $C^{1/5-\varepsilon}$.

0. INTRODUCTION

In what follows \mathbb{T}^3 denotes the 3-dimensional torus, i.e. $\mathbb{T}^3 = \mathbb{S}^1 \times \mathbb{S}^1 \times \mathbb{S}^1$. In this note we give a proof of the following theorem.

Theorem 0.1. *Assume $e : [0, 1] \rightarrow \mathbb{R}$ is a positive smooth function and ε a positive number. Then there is a continuous vector field $v \in C^{1/5-\varepsilon}(\mathbb{T}^3 \times [0, 1], \mathbb{R}^3)$ and a continuous scalar field $p \in C^{2/5-2\varepsilon}(\mathbb{T}^3 \times [0, 1])$ which solve the incompressible Euler equations*

$$\begin{cases} \partial_t v + \operatorname{div}(v \otimes v) + \nabla p = 0 \\ \operatorname{div} v = 0 \end{cases} \quad (1)$$

in the sense of distributions and such that

$$e(t) = \int |v|^2(x, t) dx \quad \forall t \in [0, 1]. \quad (2)$$

Results of this type are associated with the famous conjecture of Onsager. In a nutshell, the question is about whether or not weak solutions in a given regularity class satisfy the law of energy conservation or not. For classical

solutions (say, $v \in C^1$) we can multiply (1) by v itself, integrate by parts and obtain the energy balance

$$\int_{\mathbb{T}^3} |v(x, t)|^2 dx = \int_{\mathbb{T}^3} |v(x, 0)|^2 dx \quad \text{for all } t > 0. \quad (3)$$

On the other hand, for weak solutions (say, merely $v \in L^2$) (3) might be violated, and this possibility has been considered for a rather long time in the context of 3 dimensional turbulence. In his famous note [17] about statistical hydrodynamics, Onsager considered weak solutions satisfying the Hölder condition

$$|v(x, t) - v(x', t)| \leq C|x - x'|^\theta, \quad (4)$$

where the constant C is independent of $x, x' \in \mathbb{T}^3$ and t . He conjectured that

- (a) Any weak solution v satisfying (4) with $\theta > \frac{1}{3}$ conserves the energy;
- (b) For any $\theta < \frac{1}{3}$ there exist weak solutions v satisfying (4) which do not conserve the energy.

This conjecture is also very closely related to Kolmogorov's famous K41 theory [16] for homogeneous isotropic turbulence in 3 dimensions. We refer the interested reader to [14, 18, 13]. Part (a) of the conjecture is by now fully resolved: it has first been considered by Eyink in [12] following Onsager's original calculations and proved by Constantin, E and Titi in [2]. Slightly weaker assumptions on v (in Besov spaces) were subsequently shown to be sufficient for energy conservation in [11, 1].

In this paper we are concerned with part (b) of the conjecture. Weak solutions violating the energy equality have been constructed for a long time, starting with the seminal work of Scheffer and Shnirelman [19, 20]. In [6, 7] a new point of view was introduced, relating the issue of energy conservation to Gromov's h-principle, see also [9]. In [10] and [8] the first constructions of continuous and Hölder-continuous weak solutions violating the energy equality appeared. In particular in [8] the authors proved Theorem 0.1 with Hölder exponent $1/10 - \varepsilon$ replacing $1/5 - \varepsilon$.

The threshold exponent $\frac{1}{5}$ has been recently reached by P. Isett in [15] (although strictly speaking he proves a variant of Theorem 0.1, since he shows the existence of nontrivial solutions which are compactly supported in time, rather than prescribing the total kinetic energy). Our aim in this note is to give a shorter proof of Isett's improvement in the Hölder exponent and isolate the main new ideas of [15] compared to [10, 8]. We observe in passing that the arguments given here can be easily modified to produce nontrivial solutions with compact support in time, but losing control on the exact shape of the energy. The question of producing a solution matching an energy profile e which might vanish is subtler. A similar issue has been recently treated in the paper [5].

0.1. Euler-Reynolds system and the convex integration scheme.

Let us recall the main ideas, on which the constructions in [10, 8] are based.

The proof is achieved through an iteration scheme. At each step $q \in \mathbb{N}$ we construct a triple $(v_q, p_q, \mathring{R}_q)$ solving the Euler-Reynolds system (see [10, Definition 2.1]):

$$\begin{cases} \partial_t v_q + \operatorname{div}(v_q \otimes v_q) + \nabla p_q = \operatorname{div} \mathring{R}_q \\ \operatorname{div} v_q = 0. \end{cases} \quad (5)$$

The *size* of the perturbation

$$w_q := v_q - v_{q-1}$$

will be measured by two parameters: $\delta_q^{1/2}$ is the *amplitude* and λ_q the *frequency*. More precisely, denoting the (spatial) Hölder norms by $\|\cdot\|_k$ (see Section A for precise definitions),

$$\|w_q\|_0 \leq M\delta_q^{1/2}, \quad (6)$$

$$\|w_q\|_1 \leq M\delta_q^{1/2}\lambda_q, \quad (7)$$

and similarly,

$$\|p_q - p_{q-1}\|_0 \leq M^2\delta_q, \quad (8)$$

$$\|p_q - p_{q-1}\|_1 \leq M^2\delta_q\lambda_q, \quad (9)$$

where M is a constant depending only on the function $e = e(t)$ in the Theorem.

In constructing the iteration the new perturbation, w_{q+1} will be chosen so as to balance the previous Reynolds error \mathring{R}_q , in the sense that (c.f. equation (5)) we have $\|w_{q+1} \otimes w_{q+1}\|_0 \sim \|\mathring{R}_q\|_0$. This is formalized as

$$\|\mathring{R}_q\|_0 \leq \eta\delta_{q+1}, \quad (10)$$

$$\|\mathring{R}_q\|_1 \leq M\delta_{q+1}\lambda_q, \quad (11)$$

where η will be a small constant, again only depending on $e = e(t)$ in the Theorem. Estimates of type (6)-(11) appear already in the paper [8]: although the bound claimed for $\|\mathring{R}_1\|_1$ in the main proposition of [8] is the weaker one $\|\mathring{R}_q\|_1 \leq M\delta_{q+1}^{1/2}\lambda_q$ (cf. [8, Proposition 2.2]): λ_q here corresponds to $(D\delta/\bar{\delta}^2)^{1+\varepsilon}$ there), this was just done for the ease of notation and the actual bound achieved in the proof does in fact correspond to (11) (cf. Step 4 in Section 9). In the language of [15] the estimates (6)-(11) correspond to the frequency energy levels of order 0 and 1 (cf. Definition 9.1 therein).

Along the iteration we will have

$$\delta_q \rightarrow 0 \quad \text{and} \quad \lambda_q \rightarrow \infty$$

at a rate that is *at least* exponential. On the one hand (6), (8) and (10) will imply the convergence of the sequence v_q to a continuous weak solution of the Euler equations. On the other hand the precise dependence of λ_q on δ_q

will determine the critical Hölder regularity. Finally, the equation (2) will be ensured by

$$\left| e(t)(1 - \delta_{q+1}) - \int |v_q|^2(x, t) dx \right| \leq \frac{1}{4} \delta_{q+1} e(t). \quad (12)$$

Note that, being an expression quadratic in v_q , this estimate is consistent with (10).

As for the perturbation, it will consist essentially of a finite sum of modulated Beltrami modes (see Section 1 below), so that

$$w_q(x, t) = \sum_k a_k(x, t) \phi_k(x, t) B_k e^{i\lambda_q k \cdot x},$$

where a_k is the amplitude, ϕ_k is a phase function (i.e. $|\phi_k| = 1$) and $B_k e^{i\lambda_q k \cdot x}$ is a complex Beltrami mode at frequency λ_q . Having a perturbation of this form ensures that the “oscillation part of the error”

$$\operatorname{div}(w_q \otimes w_q + \mathring{R}_{q-1})$$

in the equation (5) vanishes, see [10] (Isett in [15] calls this term “high-high interaction”). The main analytical part of the argument goes in to choosing a_k and ϕ_k correctly in order to deal with the so-called transport part of the error

$$\partial_t w_q + v_{q-1} \cdot \nabla w_q.$$

In [10, 8] a second large parameter $\mu (= \mu_q)$ was introduced to deal with this term. In some sense the role of μ is to interpolate between errors of order 1 in the transport term and errors of order λ_q^{-1} in the oscillation term.

The technique used in [8] for the transport term leads to the Hölder exponent $\frac{1}{10}$. In our opinion the key new idea introduced by Isett is to recognize that the transport error can be reduced by defining a_k and ϕ_k in such a way that adheres more closely to the transport structure of the equation. This requires two new ingredients. First, the phase functions ϕ_k are defined using the flow map of the vector field v_q , whereas in [8] they were functions of v_q itself. With the latter choice, although some improvement of the exponent $1/10$ is possible, the threshold $1/5$ seems beyond reach. Secondly, Isett introduces a new set of estimates to complement (6)-(12) with the purpose of controlling the free transport evolution of the Reynolds error:

$$\|\partial_t \mathring{R}_q + v_q \cdot \nabla \mathring{R}_q\|_0 \leq \delta_{q+1} \delta_q^{1/2} \lambda_q. \quad (13)$$

These two ingredients play a key role also in the proof of Theorem 0.1 given here; however, compared to [15], we improve upon the simplicity of their implementation. In order to compare our proof to Isett’s proof, it is worth to notice that the parameter μ corresponds to the inverse of the life-span parameter τ used in [15].

0.2. Improvements. Although the construction of Isett in [15] is essentially based on this same scheme outlined here, there are a number of further points of departure. For instance, Isett considers perturbations with a nonlinear phase rather than the simple stationary flows used here, and consequently, he uses a “microlocal” version of the Beltrami flows. This also leads to the necessity of appealing to nonlinear stationary phase lemmas. Our purpose here is to show that, although the other ideas exploited in [15] are of independent interest and might also, in principle, lead to better bounds in the future, with the additional control in (13), a scheme much more similar to the one introduced in [10] provides a substantially shorter proof of Theorem 0.1. To this end, however, we introduce some new devices which greatly simplifies the relevant estimates:

- (a) We regularize the maps v_q and \mathring{R}_q in space only and then solve locally in time the free-transport equation in order to approximate \mathring{R}_q .
- (b) Our maps a_k are then elementary algebraic functions of the approximation of \mathring{R}_q .
- (c) The estimates for the Reynolds stress are still carried on based on simple stationary “linear” phase arguments.
- (d) The proof of (13) is simplified by one commutator estimate which, in spite of having a classical flavor, deals efficiently with one important error term.

0.3. The main iteration proposition and the proof of Theorem 0.1.

Having outlined the general idea above, we proceed with the iteration, starting with the trivial solution $(v_0, p_0, \mathring{R}_0) = (0, 0, 0)$. We will construct new triples $(v_q, p_q, \mathring{R}_q)$ inductively, assuming the estimates (6)-(13).

Proposition 0.2. *There are positive constants M and η depending only on e such that the following holds. For every $c > \frac{5}{2}$ and $b > 1$, if a is sufficiently large, then there is a sequence of triples $(v_q, p_q, \mathring{R}_q)$ starting with $(v_0, p_0, \mathring{R}_0) = (0, 0, 0)$, solving (5) and satisfying the estimates (6)-(13), where $\delta_q := a^{-b^q}$, $\lambda_q \in [a^{cb^{q+1}}, 2a^{cb^{q+1}}]$ for $q = 0, 1, 2, \dots$. In addition we claim the estimates*

$$\|\partial_t(v_q - v_{q-1})\|_0 \leq C\delta_q^{1/2}\lambda_q \quad \text{and} \quad \|\partial_t(p_q - p_{q-1})\|_0 \leq C\delta_q\lambda_q \quad (14)$$

Proof of Theorem 0.1. Choose any $c > \frac{5}{2}$ and $b > 1$ and let $(v_q, p_q, \mathring{R}_q)$ be a sequence as in Proposition 0.2. It follows then easily that $\{(v_q, p_q)\}$ converge uniformly to a pair of continuous functions (v, p) such that (1) and (2) hold. We introduce the notation $\|\cdot\|_{C^\vartheta}$ for Hölder norms in space and time. From (6)-(9), (14) and interpolation we conclude

$$\|v_{q+1} - v_q\|_{C^\vartheta} \leq M\delta_{q+1}^{1/2}\lambda_{q+1}^\vartheta \leq Ca^{b^{q+1}(2cb^\vartheta-1)/2} \quad (15)$$

$$\|p_{q+1} - p_q\|_{C^{2\vartheta}} \leq M^2\delta_{q+1}\lambda_{q+1}^{2\vartheta} \leq Ca^{b^{q+1}(2cb^{2\vartheta}-1)}. \quad (16)$$

Thus, for every $\vartheta < \frac{1}{2bc}$, v_q converges in C^ϑ and p_q in $C^{2\vartheta}$. \square

0.4. Plan of the paper. In the rest of the paper we will use D and ∇ for differentiation in the space variables and ∂_t for differentiation in the time variable. After recalling in Section 1 some preliminary notation from the paper [10], in Section 2 we give the precise definition of the maps $(v_{q+1}, p_{q+1}, \mathring{R}_{q+1})$ assuming the triple $(v_q, p_q, \mathring{R}_q)$ to be known. The Sections 3, 4 and 5 will focus on estimating, respectively, $w_{q+1} = v_{q+1} - v_q$, $\int |v_{q+1}|^2(x, t) dx$ and \mathring{R}_{q+1} . These estimates are then collected in Section 6 where Proposition 0.2 will be finally proved. The appendix collects several technical (and, for the most part, well-known) estimates on the different classical PDEs involved in our construction, i.e. the transport equation, the Poisson equation and the biLaplace equation.

0.5. Acknowledgements. We wish to thank Phil Isett for several very interesting discussions and suggestions for improvements on this manuscript.

T.B. and L.Sz. acknowledge the support of the ERC Grant Agreement No. 277993, C.dL. acknowledges the support of the SNF Grant 129812.

1. PRELIMINARIES

1.1. Geometric preliminaries. In this paper we denote by $\mathbb{R}^{n \times n}$, as usual, the space of $n \times n$ matrices, whereas $\mathcal{S}^{n \times n}$ and $\mathcal{S}_0^{n \times n}$ denote, respectively, the corresponding subspaces of symmetric matrices and of trace-free symmetric matrices. The 3×3 identity matrix will be denoted with Id . For definitiveness we will use the matrix operator norm $|R| := \max_{|v|=1} |Rv|$. Since we will deal with symmetric matrices, we have the identity $|R| = \max_{|v|=1} |Rv \cdot v|$.

Proposition 1.1 (Beltrami flows). *Let $\bar{\lambda} \geq 1$ and let $A_k \in \mathbb{R}^3$ be such that*

$$A_k \cdot k = 0, |A_k| = \frac{1}{\sqrt{2}}, A_{-k} = A_k$$

for $k \in \mathbb{Z}^3$ with $|k| = \bar{\lambda}$. Furthermore, let

$$B_k = A_k + i \frac{k}{|k|} \times A_k \in \mathbb{C}^3.$$

For any choice of $a_k \in \mathbb{C}$ with $\overline{a_k} = a_{-k}$ the vector field

$$W(\xi) = \sum_{|k|=\bar{\lambda}} a_k B_k e^{ik \cdot \xi} \quad (17)$$

is real-valued, divergence-free and satisfies

$$\text{div}(W \otimes W) = \nabla \frac{|W|^2}{2}. \quad (18)$$

Furthermore

$$\langle W \otimes W \rangle = \oint_{\mathbb{T}^3} W \otimes W d\xi = \frac{1}{2} \sum_{|k|=\bar{\lambda}} |a_k|^2 \left(\text{Id} - \frac{k}{|k|} \otimes \frac{k}{|k|} \right). \quad (19)$$

The proof of (18), which is quite elementary and can be found in [10], is based on the following algebraic identity, which we state separately for future reference:

Lemma 1.2. *Let $k, k' \in \mathbb{Z}^3$ with $|k| = |k'| = \bar{\lambda}$ and let $B_k, B_{k'} \in \mathbb{C}^3$ be the associated vectors from Proposition 1.1. Then we have*

$$(B_k \otimes B_{k'} + B_{k'} \otimes B_k)(k + k') = (B_k \cdot B_{k'})(k + k').$$

Proof. The proof is a straight-forward calculation. Indeed, since $B_k \cdot k = B_{k'} \cdot k' = 0$, we have

$$\begin{aligned} (B_k \otimes B_{k'} + B_{k'} \otimes B_k)(k + k') &= (B_{k'} \cdot k)B_k + (B_k \cdot k')B_{k'} \\ &= -B_k \times (k' \times B_{k'}) - B_{k'} \times (k \times B_k) + (B_k \cdot B_{k'})(k + k') \\ &= i\bar{\lambda}(B_k \times B_{k'} + B_{k'} \times B_k) + (B_k \cdot B_{k'})(k + k'), \end{aligned}$$

where the last equality follows from

$$k \times B_k = -i\bar{\lambda}B_k \text{ and } k' \times B_{k'} = -i\bar{\lambda}B_{k'}.$$

□

Another important ingredient is the following geometric lemma, also taken from [10].

Lemma 1.3 (Geometric Lemma). *For every $N \in \mathbb{N}$ we can choose $r_0 > 0$ and $\bar{\lambda} > 1$ with the following property. There exist pairwise disjoint subsets*

$$\Lambda_j \subset \{k \in \mathbb{Z}^3 : |k| = \bar{\lambda}\} \quad j \in \{1, \dots, N\}$$

and smooth positive functions

$$\gamma_k^{(j)} \in C^\infty(B_{r_0}(\text{Id})) \quad j \in \{1, \dots, N\}, k \in \Lambda_j$$

such that

- (a) $k \in \Lambda_j$ implies $-k \in \Lambda_j$ and $\gamma_k^{(j)} = \gamma_{-k}^{(j)}$;
- (b) For each $R \in B_{r_0}(\text{Id})$ we have the identity

$$R = \frac{1}{2} \sum_{k \in \Lambda_j} \left(\gamma_k^{(j)}(R) \right)^2 \left(\text{Id} - \frac{k}{|k|} \otimes \frac{k}{|k|} \right) \quad \forall R \in B_{r_0}(\text{Id}). \quad (20)$$

1.2. The operator \mathcal{R} . Following [10], we introduce the following operator in order to deal with the Reynolds stresses.

Definition 1.4. *Let $v \in C^\infty(\mathbb{T}^3, \mathbb{R}^3)$ be a smooth vector field. We then define $\mathcal{R}v$ to be the matrix-valued periodic function*

$$\mathcal{R}v := \frac{1}{4} (\nabla \mathcal{P}u + (\nabla \mathcal{P}u)^T) + \frac{3}{4} (\nabla u + (\nabla u)^T) - \frac{1}{2} (\text{div } u) \text{Id},$$

where $u \in C^\infty(\mathbb{T}^3, \mathbb{R}^3)$ is the solution of

$$\Delta u = v - \oint_{\mathbb{T}^3} v \text{ in } \mathbb{T}^3$$

with $\oint_{\mathbb{T}^3} u = 0$ and \mathcal{P} is the Leray projection onto divergence-free fields with zero average.

Lemma 1.5 ($\mathcal{R} = \text{div}^{-1}$). *For any $v \in C^\infty(\mathbb{T}^3, \mathbb{R}^3)$ we have*

- (a) $\mathcal{R}v(x)$ is a symmetric trace-free matrix for each $x \in \mathbb{T}^3$;
- (b) $\text{div } \mathcal{R}v = v - \oint_{\mathbb{T}^3} v$.

2. THE INDUCTIVE STEP

In this section we specify the inductive procedure which allows to construct $(v_{q+1}, p_{q+1}, \mathring{R}_{q+1})$ from $(v_q, p_q, \mathring{R}_q)$. Note that the choice of the sequences $\{\delta_q\}_{q \in \mathbb{N}}$ and $\{\lambda_q\}_{q \in \mathbb{N}}$ specified in Proposition 0.2 implies that, for a sufficiently large $a > 1$, depending only on $b > 1$ and $c > 5/2$, we have:

$$\sum_{j \leq q} \delta_j \lambda_j \leq 2\delta_q \lambda_q, \quad 1 \leq \sum_{j \leq q} \delta_j^{1/2} \lambda_j \leq 2\delta_q^{1/2} \lambda_q, \quad \sum_j \delta_j \leq \sum_j \delta_j^{1/2} \leq 2. \quad (21)$$

Since we are concerned with a single step in the iteration, with a slight abuse of notation we will write (v, p, \mathring{R}) for $(v_q, p_q, \mathring{R}_q)$ and $(v_1, p_1, \mathring{R}_1)$ for $(v_{q+1}, p_{q+1}, \mathring{R}_{q+1})$. Our inductive hypothesis implies then the following set of estimates:

$$\|v\|_0 \leq 2M, \quad \|v\|_1 \leq 2M\delta_q^{1/2} \lambda_q, \quad (22)$$

$$\|\mathring{R}\|_0 \leq \eta\delta_{q+1}, \quad \|\mathring{R}\|_1 \leq M\delta_{q+1} \lambda_q, \quad (23)$$

$$\|p\|_0 \leq 2M^2, \quad \|p\|_1 \leq 2M^2\delta_q \lambda_q, \quad (24)$$

and

$$\|(\partial_t + v \cdot \nabla)\mathring{R}\|_0 \leq M\delta_{q+1}\delta_q^{1/2} \lambda_q. \quad (25)$$

The new velocity v_1 will be defined as a sum

$$v_1 := v + w_o + w_c,$$

where w_o is the principal perturbation and w_c is a corrector. The “principal part” of the perturbation w will be a sum of Beltrami flows

$$w_o(t, x) := \sum_{|k|=\lambda_0} a_k \phi_k B_k e^{i\lambda_{q+1} k \cdot x},$$

where $B_k e^{i\lambda_{q+1} k \cdot x}$ is a single Beltrami mode at frequency λ_{q+1} , with phase shift $\phi_k = \phi_k(t, x)$ (i.e. $|\phi_k| = 1$) and amplitude $a_k = a_k(t, x)$. In the following subsections we will define a_k and ϕ_k .

2.1. Space regularization of v and R . We fix a symmetric non-negative convolution kernel $\psi \in C_c^\infty(\mathbb{R}^3)$ and a small parameter ℓ (whose choice will be specified later). Define $v_\ell := v * \psi_\ell$ and $\mathring{R}_\ell := \mathring{R} * \psi_\ell$, where the convolution is in the x variable only. Standard estimates on regularizations by convolution lead to the following:

$$\|v - v_\ell\|_0 \leq C \delta_q^{1/2} \lambda_q \ell, \quad (26)$$

$$\|\mathring{R} - \mathring{R}_\ell\|_0 \leq C \delta_{q+1} \ell, \quad (27)$$

and for any $N \geq 1$ there exists a constant $C = C(N)$ so that

$$\|v_\ell\|_N \leq C \delta_q^{1/2} \lambda_q \ell^{1-N}, \quad (28)$$

$$\|\mathring{R}_\ell\|_N \leq C \delta_{q+1} \lambda_q \ell^{1-N}. \quad (29)$$

2.2. Time discretization and transport for the Reynolds stress.

Next, we fix a smooth cut-off function $\chi \in C_c^\infty((-\frac{3}{4}, \frac{3}{4}))$ such that

$$\sum_{l \in \mathbb{Z}} \chi^2(x - l) = 1,$$

and a large parameter $\mu \in \mathbb{N} \setminus \{0\}$, whose choice will be specified later.

For any $l \in [0, \mu]$ we define

$$\rho_l := \frac{1}{3(2\pi)^3} \left(e(l\mu^{-1}) (1 - \delta_{q+2}) - \int_{\mathbb{T}^3} |v|^2(x, l\mu^{-1}) dx \right).$$

Note that (12) implies

$$\frac{1}{3(2\pi)^3} e(l\mu^{-1}) (\frac{3}{4}\delta_{q+1} - \delta_{q+2}) \leq \rho_l \leq \frac{1}{3(2\pi)^3} e(l\mu^{-1}) (\frac{5}{4}\delta_{q+1} - \delta_{q+2}).$$

We will henceforth assume

$$\delta_{q+2} \leq \frac{1}{2}\delta_{q+1},$$

so that we obtain

$$C_0^{-1}(\min e)\delta_{q+1} \leq \rho_l \leq C_0(\max e)\delta_{q+1}, \quad (30)$$

where C_0 is an absolute constant.

Finally, define $R_{\ell,l}$ to be the unique solution to the transport equation

$$\begin{cases} \partial_t \mathring{R}_{\ell,l} + v_\ell \cdot \nabla \mathring{R}_{\ell,l} = 0 \\ \mathring{R}_{\ell,l}(x, \frac{l}{\mu}) = \mathring{R}_\ell(x, \frac{l}{\mu}). \end{cases} \quad (31)$$

and set

$$R_{\ell,l}(x, t) := \rho_l \text{Id} - \mathring{R}_{\ell,l}(x, t). \quad (32)$$

2.3. The maps v_1, w, w_o and w_c . We next consider v_ℓ as a 2π -periodic function on $\mathbb{R}^3 \times [0, 1]$ and, for every $l \in [0, \mu]$, we let $\Phi_l : \mathbb{R}^3 \times [0, 1] \rightarrow \mathbb{R}^3$ be the solution of

$$\begin{cases} \partial_t \Phi_l + v_\ell \cdot \nabla \Phi_l = 0 \\ \Phi_l(x, l\mu^{-1}) = x \end{cases} \quad (33)$$

Observe that $\Phi_l(\cdot, t)$ is the inverse of the flow of the periodic vector-field v_ℓ , starting at time $t = l\mu^{-1}$ as the identity. Thus, if $y \in (2\pi\mathbb{Z})^3$, then $\Phi_l(x, t) - \Phi_l(x+y, t) \in (2\pi\mathbb{Z})^3$: $\Phi_l(\cdot, t)$ can hence be thought as a diffeomorphism of \mathbb{T}^3 onto itself and, for every $k \in \mathbb{Z}^3$, the map $\mathbb{T}^3 \times [0, 1] \ni (x, t) \rightarrow e^{i\lambda_{q+1}k \cdot \Phi_l(x, t)}$ is well-defined.

We next apply Lemma 1.3 with $N = 2$, denoting by Λ^e and Λ^o the corresponding families of frequencies in \mathbb{Z}^3 , and set $\Lambda := \Lambda^o + \Lambda^e$. For each $k \in \Lambda$ and each $l \in \mathbb{Z} \cap [0, \mu]$ we then set

$$\chi_l(t) := \chi(\mu(t - l)), \quad (34)$$

$$a_{kl}(x, t) := \sqrt{\rho_l} \gamma_k \left(\frac{R_{\ell, l}(x, t)}{\rho_l} \right), \quad (35)$$

$$w_{kl}(x, t) := a_{kl}(x, t) B_k e^{i\lambda_{q+1}k \cdot \Phi_l(x, t)}. \quad (36)$$

The “principal part” of the perturbation w consists of the map

$$w_o(x, t) := \sum_{l \text{ odd}, k \in \Lambda^o} \chi_l(t) w_{kl}(x, t) + \sum_{l \text{ even}, k \in \Lambda^e} \chi_l(t) w_{kl}(x, t). \quad (37)$$

From now on, in order to make our notation simpler, we agree that the pairs of indices $(k, l) \in \Lambda \times [0, \mu]$ which enter in our summations satisfy always the following condition: $k \in \Lambda^e$ when l is even and $k \in \Lambda^o$ when l is odd.

It will be useful to introduce the “phase”

$$\phi_{kl}(x, t) = e^{i\lambda_{q+1}k \cdot [\Phi_l(x, t) - x]}, \quad (38)$$

with which we obviously have

$$\phi_{kl} \cdot e^{i\lambda_{q+1}k \cdot x} = e^{i\lambda_{q+1}k \cdot \Phi_l}.$$

Since $R_{\ell, l}$ and Φ_l are defined as solutions of the transport equations (31) and (33), we have

$$(\partial_t + v_\ell \cdot \nabla) a_{kl} = 0 \quad \text{and} \quad (\partial_t + v_\ell \cdot \nabla) e^{i\lambda_{q+1}k \cdot \Phi_l(x, t)} = 0, \quad (39)$$

hence also

$$(\partial_t + v_\ell \cdot \nabla) w_{kl} = 0. \quad (40)$$

The corrector w_c is then defined in such a way that $w := w_o + w_c$ is divergence free:

$$\begin{aligned} w_c &:= \sum_{kl} \frac{\chi_l}{\lambda_{q+1}} \operatorname{curl} \left(i a_{kl} \phi_{kl} \frac{k \times B_k}{|k|^2} \right) e^{i\lambda_{q+1}k \cdot x} \\ &= \sum_{kl} \chi_l \left(\frac{i}{\lambda_{q+1}} \nabla a_{kl} - a_{kl} (D\Phi_l - \operatorname{Id})k \right) \times \frac{k \times B_k}{|k|^2} e^{i\lambda_{q+1}k \cdot \Phi_l} \end{aligned} \quad (41)$$

Remark 1. To see that $w = w_o + w_c$ is divergence-free, just note that, since $k \cdot B_k = 0$, we have $k \times (k \times B_k) = -|k|^2 B_k$ and hence w can be written as

$$w = \frac{1}{\lambda_{q+1}} \sum_{(k,l)} \chi_l \operatorname{curl} \left(i a_{kl} \phi_{kl} \frac{k \times B_k}{|k|^2} e^{i\lambda_{q+1}k \cdot x} \right) \quad (42)$$

For future reference it is useful to introduce the notation

$$L_{kl} := a_{kl} B_k + \left(\frac{i}{\lambda_{q+1}} \nabla a_{kl} - a_{kl} (D\Phi_l - \operatorname{Id})k \right) \times \frac{k \times B_k}{|k|^2}, \quad (43)$$

so that the perturbation w can be written as

$$w = \sum_{kl} \chi_l L_{kl} e^{i\lambda_{q+1}k \cdot \Phi_l}. \quad (44)$$

Moreover, we will frequently deal with the transport derivative with respect to the regularized flow v_ℓ of various expressions, and will henceforth use the notation

$$D_t := \partial_t + v_\ell \cdot \nabla.$$

2.4. Determination of the constants η and M . In order to determine η , first of all recall from Lemma 1.3 that the functions a_{kl} are well-defined provided

$$\left| \frac{R_{\ell,l}}{\rho_l} - \operatorname{Id} \right| \leq r_0,$$

where r_0 is the constant of Lemma 1.3. Recalling the definition of $R_{\ell,l}$ we easily deduce from the maximum principle for transport equations (c.f. (111) in Proposition B.1) that $\|\dot{R}_{\ell,l}\|_0 \leq \|\dot{R}\|_0$. Hence, from (10) and (30) we obtain

$$\left| \frac{R_{\ell,l}}{\rho_l} - \operatorname{Id} \right| \leq C_0 \frac{\eta}{\min e},$$

and thus we will require that

$$C_0 \frac{\eta}{\min e} \leq \frac{r_0}{4}.$$

The constant M in turn is determined by comparing the estimate (6) for $q+1$ with the definition of the principal perturbation w_o in (37). Indeed, using (34)-(37) and (30) we have $\|w_o\|_0 \leq C_0 |\Lambda| (\max e) \delta_{q+1}^{1/2}$. We therefore set

$$M = 2C_0 |\Lambda| (\max e),$$

so that

$$\|w_o\|_0 \leq \frac{M}{2} \delta_{q+1}^{1/2}. \quad (45)$$

2.5. The pressure p_1 and the Reynolds stress \mathring{R}_1 . We set

$$\mathring{R}_1 = R^0 + R^1 + R^2 + R^3 + R^4 + R^5,$$

where

$$R^0 = \mathcal{R}(\partial_t w + v_\ell \cdot \nabla w + w \cdot \nabla v_\ell) \quad (46)$$

$$R^1 = \mathcal{R} \operatorname{div} \left(w_o \otimes w_o - \sum_l \chi_l^2 R_{\ell,l} - \frac{|w_o|^2}{2} \operatorname{Id} \right) \quad (47)$$

$$R^2 = w_o \otimes w_c + w_c \otimes w_o + w_c \otimes w_c - \frac{|w_c|^2 + 2\langle w_o, w_c \rangle}{3} \operatorname{Id} \quad (48)$$

$$R^3 = w \otimes (v - v_\ell) + (v - v_\ell) \otimes w - \frac{2\langle (v - v_\ell), w \rangle}{3} \operatorname{Id} \quad (49)$$

$$R^4 = \mathring{R} - \mathring{R}_\ell \quad (50)$$

$$R^5 = \sum_l \chi_l^2 (\mathring{R}_\ell - \mathring{R}_{\ell,\ell}). \quad (51)$$

Observe that \mathring{R}_1 is indeed a traceless symmetric tensor. The corresponding form of the new pressure will then be

$$p_1 = p - \frac{|w_o|^2}{2} - \frac{1}{3}|w_c|^2 - \frac{2}{3}\langle w_o, w_c \rangle - \frac{2}{3}\langle v - v_\ell, w \rangle. \quad (52)$$

Recalling (32) we see that $\sum_l \chi_l^2 \operatorname{tr} R_{\ell,l}$ is a function of time only. Since also $\sum_l \chi_l^2 = 1$, it is then straightforward to check that

$$\begin{aligned} \operatorname{div} \mathring{R}_1 - \nabla p_1 &= \partial_t w + \operatorname{div} (v \otimes w + w \otimes v + w \otimes w) + \operatorname{div} \mathring{R} - \nabla p \\ &= \partial_t w + \operatorname{div} (v \otimes w + w \otimes v + w \otimes w) + \partial_t v + \operatorname{div} (v \otimes v) \\ &= \partial_t v_1 + \operatorname{div} v_1 \otimes v_1. \end{aligned}$$

The following lemma will play a key role.

Lemma 2.1. *The following identity holds:*

$$w_o \otimes w_o = \sum_l \chi_l^2 R_{\ell,l} + \sum_{(k,l),(k',l'), k \neq -k'} \chi_l \chi_{l'} w_{kl} \otimes w_{k'l'}. \quad (53)$$

Proof. Recall that the pairs (k, l) , (k', l') are chosen so that $k \neq -k'$ if l is even and l' is odd. Moreover $\chi_l \chi_{l'} = 0$ if l and l' are distinct and have the same parity. Hence the claim follows immediately from our choice of a_{kl} in (35) and Proposition 1.1 and Lemma 1.3 (c.f. [10, Proposition 6.1(ii)]). \square

2.6. Conditions on the parameters - hierarchy of length-scales. In the next couple of sections we will need to estimate various expressions involving v_ℓ and w . To simplify the formulas that we arrive at, we will from now on assume the following conditions on $\mu, \lambda_{q+1} \geq 1$ and $\ell \leq 1$:

$$\frac{\delta_q^{1/2} \lambda_q \ell}{\delta_{q+1}^{1/2}} \leq 1, \quad \frac{\delta_q^{1/2} \lambda_q}{\mu} + \frac{1}{\ell \lambda_{q+1}} \leq \lambda_{q+1}^{-\beta} \quad \text{and} \quad \frac{1}{\lambda_{q+1}} \leq \frac{\delta_q^{1/2}}{\mu}. \quad (54)$$

These conditions imply the following orderings of length scales, which will be used to simplify the estimates in Section 3:

$$\frac{1}{\lambda_{q+1}} \leq \frac{\delta_q^{1/2}}{\mu} \leq \frac{1}{\lambda_q} \quad \text{and} \quad \frac{1}{\lambda_{q+1}} \leq \ell \leq \frac{1}{\lambda_q}. \quad (55)$$

One can think of these chains of inequalities as an ordering of various length scales involved in the definition of v_1 .

Remark 2. *The most relevant and restrictive condition is $\frac{\delta_q^{1/2}}{\mu} \leq \frac{1}{\lambda_q}$. Indeed, this condition can be thought of as a kind of CFL condition (cf. [4]), restricting the coarse-grained flow to times of the order of $|\nabla v|^{-1}$, c.f. Lemma 3.1 and in particular (57) below. Assuming only this condition on the parameters, essentially all the arguments for estimating the various terms would still follow through. The remaining inequalities are only used to simplify the many estimates needed in the rest of the paper, which otherwise would have a much more complicated dependence upon the various parameters.*

3. ESTIMATES ON THE PERTURBATION

Lemma 3.1. *Assume (54) holds. For t in the range $|\mu t - l| < 1$ we have*

$$\|D\Phi_l\|_0 \leq C \quad (56)$$

$$\|D\Phi_l - \text{Id}\|_0 \leq C \frac{\delta_q^{1/2} \lambda_q}{\mu} \quad (57)$$

$$\|D\Phi_l\|_N \leq C \frac{\delta_q^{1/2} \lambda_q}{\mu \ell^N}, \quad N \geq 1 \quad (58)$$

Moreover,

$$\|a_{kl}\|_0 + \|L_{kl}\|_0 \leq C \delta_{q+1}^{1/2} \quad (59)$$

$$\|a_{kl}\|_N \leq C \delta_{q+1}^{1/2} \lambda_q \ell^{1-N}, \quad N \geq 1 \quad (60)$$

$$\|L_{kl}\|_N \leq C \delta_{q+1}^{1/2} \ell^{-N}, \quad N \geq 1 \quad (61)$$

$$\begin{aligned} \|\phi_{kl}\|_N &\leq C \lambda_{q+1} \frac{\delta_q^{1/2} \lambda_q}{\mu \ell^{N-1}} + C \left(\frac{\delta_q^{1/2} \lambda_q \lambda_{q+1}}{\mu} \right)^N \\ &\leq C \lambda_{q+1}^{N(1-\beta)} \quad N \geq 1. \end{aligned} \quad (62)$$

Consequently, for any $N \geq 0$

$$\|w_c\|_N \leq C \delta_{q+1}^{1/2} \frac{\delta_q^{1/2} \lambda_q}{\mu} \lambda_{q+1}^N, \quad (63)$$

$$\|w_o\|_1 \leq \frac{M}{2} \delta_{q+1}^{1/2} \lambda_{q+1} + C \delta_{q+1}^{1/2} \lambda_{q+1}^{1-\beta} \quad (64)$$

$$\|w_o\|_N \leq C \delta_{q+1}^{1/2} \lambda_{q+1}^N, \quad N \geq 2 \quad (65)$$

where the constants in (56)-(57) depend only on M , the constant in (58) depends on M and N , the constants in (59) and (64) depend on M and e and the remaining constants depend on M , e and N .

Proof. The estimates (56) and (57) are direct consequences of (114) in Proposition B.1, together with (55), whereas (115) in Proposition B.1 combined with the convolution estimate (28) implies (58).

Next, (29) together with (111), (112) and (113) in Proposition B.1 and (55) leads to

$$\|R_{\ell,l}\|_0 \leq C \delta_{q+1}, \quad (66)$$

$$\|R_{\ell,l}\|_N \leq C \delta_{q+1} \lambda_q \ell^{1-N}, \quad N \geq 1. \quad (67)$$

The estimate (59) is now a consequence of (66), (57) and (30), whereas by (108) we obtain

$$\|a_{kl}\|_N \leq C \delta_{q+1}^{-1/2} \|R_{\ell,l}\|_N \leq C \delta_{q+1}^{1/2} \lambda_q \ell^{1-N} \leq C \delta_{q+1}^{1/2} \ell^{-N}. \quad (68)$$

Similarly we deduce (61) from

$$\begin{aligned} \|L_{kl}\|_N &\leq C \|a_{kl}\|_N + C \lambda_{q+1}^{-1} \|a_{kl}\|_{N+1} + \\ &\quad + C (\|a_{kl}\|_N \|D\Phi_l - \text{Id}\|_0 + \|a_{kl}\|_0 \|D\Phi_l\|_N) \end{aligned}$$

and once again using (55).

In order to prove (62) we apply (109) with $m = N$ to conclude

$$\|\phi_{kl}\|_N \leq C \lambda_{q+1} \|D\Phi_l\|_{N-1} + \lambda_{q+1}^N \|D\Phi_l - \text{Id}\|_0^N,$$

from which (62) follows using (57), (58) and (54).

Using the formula (41) together with (57), (58), (59) and (61) we conclude

$$\|w_c\|_0 \leq \frac{C}{\lambda_{q+1}} \|a_{kl}\|_1 + C \|a_{kl}\|_0 \|D\Phi_l - \text{Id}\|_0 \leq C \frac{\delta_q^{1/2} \lambda_q}{\mu}$$

and, for $N \geq 1$,

$$\begin{aligned} \|w_c\|_N &\leq C \sum_{kl} \chi_l \left(\frac{1}{\lambda_{q+1}} \|a_{kl}\|_{N+1} + \|a_{kl}\|_0 \|D\Phi_l\|_N + \|a_{kl}\|_N \|D\Phi_l - \text{Id}\|_0 \right) \\ &\quad + C \|w_c\|_0 \sum_l \chi_l (\lambda_{q+1}^N \|D\Phi_l\|_0^N + \lambda_{q+1} \|D\Phi_l\|_{N-1}) \\ &\stackrel{(55)}{\leq} C \delta_{q+1}^{1/2} \lambda_{q+1}^N \left(\frac{\lambda_q}{\lambda_{q+1}} + \frac{\delta_q^{1/2} \lambda_q}{\mu} \right) \leq C \frac{\delta_q^{1/2} \lambda_q}{\mu} \lambda_{q+1}^N. \end{aligned}$$

This proves (63). The estimates for w_o follow analogously, using in addition the choice of M and (45). \square

Lemma 3.2. *Recall that $D_t = \partial_t + v_\ell \cdot \nabla$. Under the assumptions of Lemma 3.1 we have*

$$\|D_t v_\ell\|_N \leq C \delta_q \lambda_q \ell^{-N}, \quad (69)$$

$$\|D_t L_{kl}\|_N \leq C \delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q \ell^{-N}, \quad (70)$$

$$\|D_t^2 L_{kl}\|_N \leq C \delta_{q+1}^{1/2} \delta_q \lambda_q \ell^{-N-1}, \quad (71)$$

$$\|D_t w_c\|_N \leq C \delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q \lambda_{q+1}^N, \quad (72)$$

$$\|D_t w_o\|_N \leq C \delta_{q+1}^{1/2} \mu \lambda_{q+1}^N. \quad (73)$$

Proof. Estimate on $D_t v_\ell$. Note that v_ℓ satisfies the inhomogeneous transport equation

$$\partial_t v_\ell + v_\ell \cdot \nabla v_\ell = -\nabla p * \psi_\ell + \text{div}(\mathring{R}_\ell - (v \otimes v) * \psi_\ell + v_\ell \otimes v_\ell).$$

By hypothesis $\|\nabla p * \psi_\ell\|_N \leq C \|p\|_1 \ell^{-N} \leq C \delta_q \lambda_q \ell^{-N}$ and analogously $\|\text{div} R * \psi_\ell\| \leq C \delta_{q+1} \lambda_q \ell^{-N}$. On the other hand, by Proposition C.1:

$$\|\text{div}((v \otimes v) * \psi_\ell - v_\ell \otimes v_\ell)\|_N \leq C \ell^{1-N} \|v\|_1^2 \leq C \ell^{1-N} \delta_q \lambda_q^2.$$

Thus (69) follows from (55).

Estimates on L_{kl} . Recall that L_{kl} is defined as

$$L_{kl} := a_{kl} B_k + \left(\frac{i}{\lambda_{q+1}} \nabla a_{kl} - a_{kl} (D\Phi_l - \text{Id}) k \right) \times \frac{k \times B_k}{|k|^2}.$$

Using that

$$\begin{aligned} D_t a_{kl} &= 0, \quad D_t \Phi_l = 0, \\ D_t \nabla a_{kl} &= -Dv_\ell^T \nabla a_{kl}, \quad D_t D\Phi_l = -D\Phi_l Dv_\ell, \end{aligned} \quad (74)$$

we obtain

$$D_t L_{kl} = \left(-\frac{i}{\lambda_{q+1}} Dv_\ell^T \nabla a_{kl} + a_{kl} D\Phi_l Dv_\ell k \right) \times \frac{k \times B_k}{|k|^2}.$$

Consequently, for times $|t - l| < \mu^{-1}$ and $N \geq 0$ we have

$$\begin{aligned} \|D_t L_{kl}\|_N &\leq C \delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q \ell^{-N} \left(\frac{\lambda_q}{\lambda_{q+1}} + \lambda_q \ell + \frac{\delta_q^{1/2} \lambda_q}{\mu} + 1 \right) \\ &\leq C \delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q \ell^{-N}, \end{aligned}$$

where we have used (106), Lemma 3.1 and (55). Taking one more derivative and using (74) again, we obtain

$$\begin{aligned} D_t^2 L_{kl} = & \left(-\frac{i}{\lambda_{q+1}} (D_t D v_\ell)^T \nabla a_{kl} + \frac{i}{\lambda_{q+1}} D v_\ell^T D v_\ell^T \nabla a_{kl} + \right. \\ & \left. - a_{kl} D \Phi_l D v_\ell D v_\ell k + a_{kl} D \Phi_l D_t D v_\ell k \right) \times \frac{k \times B_k}{|k|^2}. \end{aligned}$$

Note that $D_t D v_\ell = D D_t v_\ell - D v_\ell D v_\ell$, so that

$$\begin{aligned} \|D_t D v_\ell\|_N &\leq \|D_t v_\ell\|_{N+1} + \|D v_\ell\|_N \|D v_\ell\|_0 \\ &\leq C \delta_q \lambda_q \ell^{-N-1} (1 + \lambda_q \ell) \leq C \delta_q \lambda_q \ell^{-N-1}. \end{aligned}$$

It then follows from the product rule (106) and (55) that

$$\begin{aligned} \|D_t^2 L_{kl}\|_N &\leq C \delta_{q+1}^{1/2} \delta_q \lambda_q \ell^{-N-1} \left(\frac{\lambda_q}{\lambda_{q+1}} + \frac{\lambda_q^2 \ell}{\lambda_{q+1}} + \lambda_q \ell + (\lambda_q \ell)^2 + \frac{\delta_q^{1/2} \lambda_q}{\mu} + 1 \right) \\ &\leq C \delta_{q+1}^{1/2} \delta_q \lambda_q \ell^{-N-1}. \end{aligned}$$

Estimates on w_c . Observe that $w_c = \sum \chi_l (L_{kl} - a_{kl} B_k) e^{i\lambda_{q+1} k \cdot \Phi_l}$ (see (41) and (43)). Differentiating this identity we then conclude

$$\begin{aligned} D_t w_c &= \sum_{kl} \chi_l (D_t L_{kl}) e^{i\lambda_{q+1} k \cdot \Phi_l} + (\partial_t \chi_l) (L_{kl} - a_{kl} B_k) e^{i\lambda_{q+1} k \cdot \Phi_l} \\ &= \sum_{kl} \chi_l (D_t L_{kl}) \phi_{kl} e^{i\lambda_{q+1} k \cdot x} + \\ &\quad + \sum_{kl} (\partial_t \chi_l) \left(\frac{i \nabla a_{kl}}{\lambda_{q+1}} - a_{kl} (D \Phi_l - \text{Id}) k \right) \times \frac{k \times B_k}{|k|^2} \phi_{kl} e^{i\lambda_{q+1} k \cdot x}. \end{aligned}$$

Hence we obtain (72) as a consequence of Lemma 3.1 and (70).

Estimates on w_o . Using (74) we have

$$D_t w_o = \sum_{k,l} \chi'_l a_{kl} \phi_{kl} e^{i\lambda_{q+1} k \cdot x}.$$

Therefore (73) follows immediately from Lemma 3.1. \square

4. ESTIMATES ON THE ENERGY

Lemma 4.1 (Estimate on the energy).

$$\left| e(t)(1 - \delta_{q+2}) - \int_{\mathbb{T}^3} |v_1|^2 dx \right| \leq \frac{1}{\mu} + C \frac{\delta_{q+1} \delta_q^{1/2} \lambda_q}{\mu} + C \frac{\delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q}{\lambda_{q+1}}. \quad (75)$$

Proof. Define

$$\bar{e}(t) := 3(2\pi)^3 \sum_l \chi_l^2(t) \rho_l.$$

Using Lemma 2.1 we then have

$$\begin{aligned} |w_o|^2 &= \sum_l \chi_l^2 \operatorname{tr} R_{\ell, l} + \sum_{(k, l), (k', l'), k \neq -k'} \chi_l \chi_{l'} w_{kl} \cdot w_{k, l'} \\ &= (2\pi)^{-3} \bar{e} + \sum_{(k, l), (k', l'), k \neq -k'} \chi_l \chi_{k'} a_{kl} a_{k' l'} \phi_{kl} \phi_{k' l'} e^{i \lambda_{q+1} (k+k') \cdot x}. \end{aligned} \quad (76)$$

Observe that \bar{e} is a function of t only and that, since $(k+k') \neq 0$ in the sum above, we can apply Proposition E.1(i) with $m = 1$. From Lemma 3.1 we then deduce

$$\left| \int_{\mathbb{T}^3} |w_o|^2 dx - \bar{e}(t) \right| \leq C \frac{\delta_{q+1} \delta_q^{1/2} \lambda_q}{\mu} + C \frac{\delta_{q+1} \lambda_q}{\lambda_{q+1}}. \quad (77)$$

Next we recall (42), integrate by parts and use (59) and (62) to reach

$$\left| \int_{\mathbb{T}^3} v \cdot w dx \right| \leq C \frac{\delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q}{\lambda_{q+1}}. \quad (78)$$

Note also that by (63) we have

$$\int_{\mathbb{T}^3} |w_c|^2 + |w_c w_o| dx \leq C \frac{\delta_{q+1} \delta_q^{1/2} \lambda_q}{\mu}. \quad (79)$$

Summarizing, so far we have achieved

$$\begin{aligned} &\left| \int_{\mathbb{T}^3} |v_1|^2 dx - \left(\bar{e}(t) + \int_{\mathbb{T}^3} |v|^2 dx \right) \right| \stackrel{(78)}{\leq} \left| \int_{\mathbb{T}^3} |w|^2 dx - \bar{e}(t) \right| + C \frac{\delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q}{\lambda_{q+1}} \\ &\stackrel{(79)}{\leq} \left| \int_{\mathbb{T}^3} |w_o|^2 dx - \bar{e}(t) \right| + C \frac{\delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q}{\lambda_{q+1}} + C \frac{\delta_{q+1} \delta_q^{1/2} \lambda_q}{\mu} \\ &\stackrel{(77)}{\leq} C \frac{\delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q}{\lambda_{q+1}} + C \frac{\delta_{q+1} \delta_q^{1/2} \lambda_q}{\mu}. \end{aligned} \quad (80)$$

Next, recall that

$$\begin{aligned} \bar{e}(t) &= 3(2\pi)^3 \sum_l \chi_l^2 \rho_l \\ &= (1 - \delta_{q+2}) \sum_l \chi_l^2 e\left(\frac{\mu}{l}\right) - \sum_l \chi_l^2 \int_{\mathbb{T}^3} |v(x, l\mu^{-1})|^2 dx. \end{aligned}$$

Since $\left|t - \frac{l}{\mu}\right| < \mu^{-1}$ on the support of χ_l and since $\sum_l \chi_l^2 = 1$, we have

$$\left|e(t) - \sum_l \chi_l^2 e\left(\frac{l}{\mu}\right)\right| \leq \mu^{-1}.$$

Moreover, using the Euler-Reynolds equation, we can compute

$$\begin{aligned} \int_{\mathbb{T}^3} \left(|v(x, t)|^2 - |v(x, l\mu^{-1})|^2\right) dx &= \int_{\frac{l}{\mu}}^t \int_{\mathbb{T}^3} \partial_t |v|^2 \\ &= - \int_{\frac{l}{\mu}}^t \int_{\mathbb{T}^3} \operatorname{div} (v(|v|^2 + 2p)) + 2 \int_{\frac{l}{\mu}}^t \int_{\mathbb{T}^3} v \cdot \operatorname{div} \mathring{R} = -2 \int_{\frac{l}{\mu}}^t \int_{\mathbb{T}^3} Dv : \mathring{R}. \end{aligned}$$

Thus, for $\left|t - \frac{l}{\mu}\right| \leq \mu^{-1}$ we conclude

$$\left| \int_{\mathbb{T}^3} |v(x, t)|^2 - |v(x, l\mu^{-1})|^2 dx \right| \leq C \frac{\delta_{q+1} \delta_q^{1/2} \lambda_q}{\mu}.$$

Using again $\sum \chi_l^2 = 1$, we then conclude

$$\left| e(t)(1 - \delta_{q+2}) - \left(\bar{e}(t) + \int_{\mathbb{T}^3} |v(x, t)|^2 dx \right) \right| \leq \frac{1}{\mu} + C \frac{\delta_{q+1} \delta_q^{1/2} \lambda_q}{\mu}. \quad (81)$$

The desired conclusion (75) follows from (80) and (81). \square

5. ESTIMATES ON THE REYNOLDS STRESS

In this section we bound the new Reynolds Stress \mathring{R}_1 . The general pattern in estimating derivatives of the Reynolds stress is that:

- the space derivative gets an extra factor of λ_{q+1} (when the derivative falls on the exponential factor),
- the transport derivative gets an extra factor μ (when the derivative falls on the time cut-off).

In fact the transport derivative is slightly more subtle, because in R^0 a second transport derivative of the perturbation w appears, which leads to an additional term (see (92)). Nevertheless, we organize the estimates in the following proposition according to the above pattern.

Proposition 5.1. *For any choice of small positive numbers ε and β , there is a constant C (depending only upon these parameters and on e and M)*

such that, if μ , λ_{q+1} and ℓ satisfy the conditions (54), then we have

$$\|R^0\|_0 + \frac{1}{\lambda_{q+1}}\|R^0\|_1 + \frac{1}{\mu}\|D_t R^0\|_0 \leq C \frac{\delta_{q+1}^{1/2}\mu}{\lambda_{q+1}^{1-\varepsilon}} + \frac{\delta_{q+1}^{1/2}\delta_q\lambda_q}{\lambda_{q+1}^{1-\varepsilon}\mu\ell} \quad (82)$$

$$\|R^1\|_0 + \frac{1}{\lambda_{q+1}}\|R^1\|_1 + \frac{1}{\mu}\|D_t R^1\|_0 \leq C \frac{\delta_{q+1}\delta_q^{1/2}\lambda_q\lambda_{q+1}^\varepsilon}{\mu} \quad (83)$$

$$\|R^2\|_0 + \frac{1}{\lambda_{q+1}}\|R^2\|_1 + \frac{1}{\mu}\|D_t R^2\|_0 \leq C \frac{\delta_{q+1}\delta_q^{1/2}\lambda_q}{\mu} \quad (84)$$

$$\|R^3\|_0 + \frac{1}{\lambda_{q+1}}\|R^3\|_1 + \frac{1}{\mu}\|D_t R^3\|_0 \leq C \delta_{q+1}^{1/2}\delta_q^{1/2}\lambda_q\ell \quad (85)$$

$$\|R^4\|_0 + \frac{1}{\lambda_{q+1}}\|R^4\|_1 + \frac{1}{\mu}\|D_t R^4\|_0 \leq C \frac{\delta_{q+1}\delta_q^{1/2}\lambda_q}{\mu} + C \delta_{q+1}\lambda_q\ell \quad (86)$$

$$\|R^5\|_0 + \frac{1}{\lambda_{q+1}}\|R^5\|_1 + \frac{1}{\mu}\|D_t R^5\|_0 \leq C \frac{\delta_{q+1}\delta_q^{1/2}\lambda_q}{\mu}. \quad (87)$$

Thus

$$\begin{aligned} & \|\dot{R}_1\|_0 + \frac{1}{\lambda_{q+1}}\|\dot{R}_1\|_1 + \frac{1}{\mu}\|D_t \dot{R}_1\|_0 \leq \\ & \leq C \left(\frac{\delta_{q+1}^{1/2}\mu}{\lambda_{q+1}^{1-\varepsilon}} + \frac{\delta_{q+1}\delta_q^{1/2}\lambda_q\lambda_{q+1}^\varepsilon}{\mu} + \delta_{q+1}^{1/2}\delta_q^{1/2}\lambda_q\ell + \frac{\delta_{q+1}^{1/2}\delta_q\lambda_q}{\lambda_{q+1}^{1-\varepsilon}\mu\ell} \right), \end{aligned} \quad (88)$$

and, moreover,

$$\begin{aligned} & \|\partial_t \dot{R}_1 + v_1 \cdot \nabla \dot{R}_1\|_0 \leq \\ & \leq C \delta_{q+1}^{1/2}\lambda_{q+1} \left(\frac{\delta_{q+1}^{1/2}\mu}{\lambda_{q+1}^{1-\varepsilon}} + \frac{\delta_{q+1}\delta_q^{1/2}\lambda_q\lambda_{q+1}^\varepsilon}{\mu} + \delta_{q+1}^{1/2}\delta_q^{1/2}\lambda_q\ell + \frac{\delta_{q+1}^{1/2}\delta_q\lambda_q}{\lambda_{q+1}^{1-\varepsilon}\mu\ell} \right). \end{aligned} \quad (89)$$

Proof. Estimates on R^0 . We start by calculating

$$\partial_t w + v_\ell \cdot \nabla w + w \cdot \nabla v_\ell = \sum_{kl} (\chi'_l L_{kl} + \chi_l D_t L_{kl} + \chi_l L_{kl} \cdot \nabla v_\ell) e^{ik \cdot \Phi_l}.$$

Define $\Omega_{kl} := (\chi'_l L_{kl} + \chi_l D_t L_{kl} + \chi_l L_{kl} \cdot \nabla v_\ell) \phi_{kl}$ and write (recalling the identity $\phi_{kl} e^{i\lambda_{q+1}k \cdot x} = e^{i\lambda_{q+1}k \cdot \Phi_l}$),

$$\partial_t w + v_\ell \cdot \nabla w + w \cdot \nabla v_\ell = \sum_{kl} \Omega_{kl} e^{i\lambda_{q+1}k \cdot x}. \quad (90)$$

Using Lemmas 3.1 and 3.2 and (55)

$$\|\Omega_{kl}\|_0 \leq C \delta_{q+1}^{1/2}\mu \left(1 + \frac{\delta_q^{1/2}\lambda_q}{\mu} \right) \leq C \delta_{q+1}^{1/2}\mu$$

and similarly, for $N \geq 1$

$$\|\Omega_{kl}\|_N \leq C \delta_{q+1}^{1/2}\mu (\ell^{-N} + \|\phi_{kl}\|_N) \leq C \delta_{q+1}^{1/2}\mu \lambda_{q+1}^{N(1-\beta)}.$$

Moreover, observe that although this estimate has been derived for N integer, by the interpolation inequality (107) it can be easily extended to any real $N \geq 1$ (besides, this fact will be used frequently in the rest of the proof). Applying Proposition E.1(ii) we obtain

$$\begin{aligned} \|R_0\|_0 &\leq \sum_{kl} \left(\lambda_{q+1}^{\varepsilon-1} \|\Omega_{kl}\|_0 + \lambda_{q+1}^{-N+\varepsilon} [\Omega_{kl}]_N + \lambda_{q+1}^{-N} [\Omega_{kl}]_{N+\varepsilon} \right) \\ &\leq C \delta_{q+1}^{1/2} \mu \left(\lambda_{q+1}^{-1+\varepsilon} + \lambda_{q+1}^{-N\beta+\varepsilon} \right) \end{aligned} \quad (91)$$

It suffices to choose N so that $N\beta \geq 1$ in order to achieve

$$\|R^0\|_0 \leq C \delta_{q+1}^{1/2} \mu \lambda_{q+1}^{\varepsilon-1}.$$

As for $\|R^0\|_1$, we differentiate (90). We therefore conclude

$$\partial_j R^0 = \mathcal{R} \left(\sum_{kl} (i \lambda_{q+1} k_j \Omega_{kl} + \partial_j \Omega_{kl}) e^{i \lambda_{q+1} k \cdot x} \right).$$

Applying Proposition E.1(ii) as before we conclude $\|R^0\|_1 \leq C \delta_{q+1}^{1/2} \mu \lambda_{q+1}^\varepsilon$.

Estimates on $D_t R^0$. We start by calculating

$$\begin{aligned} D_t (\partial_t w + v_\ell \cdot \nabla w + w \cdot \nabla v_\ell) &= \sum_{kl} \left(\partial_t^2 \chi_l L_{kl} + 2 \partial_t \chi_l D_t L_{kl} + \chi_l D_t^2 L_{kl} + \right. \\ &\quad \left. + \partial_t \chi_l L_{kl} \cdot \nabla v_\ell + \chi_l D_t L_{kl} \cdot \nabla v_\ell + \chi_l L_{kl} \cdot \nabla D_t v_\ell - \chi_l L_{kl} \cdot \nabla v_\ell \cdot \nabla v_\ell \right) e^{ik \cdot \Phi_l} \\ &=: \sum_{kl} \Omega'_{kl} e^{i \lambda_{q+1} k \cdot x}. \end{aligned}$$

As before, we have

$$\|\Omega'_{kl}\|_0 \leq C \delta_{q+1}^{1/2} \mu \left(\mu + \frac{\delta_q \lambda_q}{\mu \ell} + \delta_q^{1/2} \lambda_q + \frac{\delta_q \lambda_q^2}{\mu} \right) \leq C \delta_{q+1}^{1/2} \left(\mu + \frac{\delta_q \lambda_q}{\mu \ell} \right) \quad (92)$$

and, for any $N \geq 1$

$$\begin{aligned} \|\Omega'_{kl}\|_N &\leq C \delta_{q+1}^{1/2} \mu \ell^{-N} \left(\mu + \frac{\delta_q \lambda_q}{\mu \ell} + \delta_q^{1/2} \lambda_q + \frac{\delta_q \lambda_q^2}{\mu} \right) + \|\Omega'_{kl}\|_0 \|\phi_{kl}\|_N \\ &\leq C \delta_{q+1}^{1/2} \mu \left(\mu + \frac{\delta_q \lambda_q}{\mu \ell} \right) (\ell^{-N} + \|\phi_{kl}\|_N) \\ &\leq C \delta_{q+1}^{1/2} \mu \left(\mu + \frac{\delta_q \lambda_q}{\mu \ell} \right) \lambda_{q+1}^{N(1-\beta)}. \end{aligned}$$

Next, observe that we can write

$$\begin{aligned}
D_t R^0 &= \left([D_t, \mathcal{R}] + \mathcal{R} D_t \right) (\partial_t w + v_\ell \cdot \nabla w + w \cdot \nabla v_\ell) \\
&= \left([v_\ell, \mathcal{R}] \nabla + \mathcal{R} D_t \right) (\partial_t w + v_\ell \cdot \nabla w + w \cdot \nabla v_\ell) \\
&= \sum_{kl} [v_\ell, \mathcal{R}] (\nabla \Omega_{kl} e^{i\lambda_{q+1} k \cdot x}) + i\lambda_{q+1} [v_\ell \cdot k, \mathcal{R}] (\Omega_{kl} e^{i\lambda_{q+1} k \cdot x}) + \mathcal{R} (\Omega'_{kl} e^{i\lambda_{q+1} k \cdot x})
\end{aligned}$$

(where, as it is customary, $[A, B]$ denotes the commutator $AB - BA$ of two operators A and B).

Using the estimates for Ω'_{kl} derived above, and applying Proposition E.1(ii), we obtain

$$\begin{aligned}
\|\mathcal{R}(\Omega'_{kl} e^{i\lambda_{q+1} k \cdot x})\|_0 &\leq \frac{\|\Omega'_{kl}\|_0}{\lambda_{q+1}^{1-\varepsilon}} + \frac{[\Omega'_{kl}]_N}{\lambda_{q+1}^{N-\varepsilon}} + \frac{[\Omega'_{kl}]_{N+\varepsilon}}{\lambda_{q+1}^N} \\
&\leq C \frac{\delta_{q+1}^{1/2} \mu}{\lambda_{q+1}^{1-\varepsilon}} \left(\mu + \frac{\delta_q \lambda_q}{\mu \ell} \right) \left(1 + \lambda_{q+1}^{1-N\beta} \right)
\end{aligned}$$

Furthermore, applying Proposition F.1 we obtain

$$\begin{aligned}
\left\| [v_\ell, \mathcal{R}] (\nabla \Omega_{kl} e^{i\lambda_{q+1} k \cdot x}) \right\|_0 &\leq C \frac{\|\Omega_{kl}\|_{N+1+\varepsilon} \|v_\ell\|_{2+\varepsilon} + \|\Omega_{kl}\|_{3+\varepsilon} \|v_\ell\|_{N+\varepsilon}}{\lambda_{q+1}^N} \\
&\quad + C \frac{\|\Omega_{kl}\|_{N+1} \|v_\ell\|_2 + \|\Omega_{kl}\|_3 \|v_\ell\|_N}{\lambda_{q+1}^{N-\varepsilon}} + C \frac{\|\Omega_{kl}\|_1 \|v_\ell\|_1}{\lambda_{q+1}^{2-\varepsilon}} \\
&\leq C \frac{\delta_{q+1}^{1/2} \mu}{\lambda_{q+1}^{1-\varepsilon}} \delta_q^{1/2} \lambda_q \left(1 + \lambda_{q+1}^{3-\beta-\beta N} \right) \leq C \frac{\delta_{q+1}^{1/2} \mu^2}{\lambda_{q+1}^{1-\varepsilon}} \left(1 + \lambda_{q+1}^{3-\beta(N+1)} \right)
\end{aligned}$$

and similarly

$$\lambda_{q+1} \left\| [v_\ell \cdot k, \mathcal{R}] (\Omega_{kl} e^{i\lambda_{q+1} k \cdot x}) \right\|_0 \leq C \frac{\delta_{q+1}^{1/2} \mu^2}{\lambda_{q+1}^{1-\varepsilon}} \left(1 + \lambda_{q+1}^{3-\beta(N+1)} \right).$$

By choosing $N \in \mathbb{N}$ sufficiently large so that

$$\beta(N+1) \geq 3 \quad \text{and} \quad \beta N \geq 1,$$

we deduce

$$\|D_t R^0\|_0 \leq C \frac{\delta_{q+1}^{1/2} \mu}{\lambda_{q+1}^{1-\varepsilon}} \left(\mu + \frac{\delta_q \lambda_q}{\mu \ell} \right)$$

This concludes the proof of (82).

Estimates on R^1 . Using Lemma 2.1 we have

$$\begin{aligned} \operatorname{div} \left(w_o \otimes w_o - \sum_l \chi_l^2 \mathring{R}_{\ell,l} - \frac{|w_o|^2}{2} \operatorname{Id} \right) &= \\ &= \sum_{\substack{(k,l),(k',l') \\ k+k' \neq 0}} \chi_l \chi_{l'} \operatorname{div} \left(w_{kl} \otimes w_{k'l'} - \frac{w_{kl} \cdot w_{k'l'}}{2} \operatorname{Id} \right) = I + II \end{aligned}$$

where, setting $f_{klk'l'} := \chi_l \chi_{l'} a_{kl} a_{k'l'} \phi_{kl} \phi_{k'l'}$,

$$\begin{aligned} I &= \sum_{\substack{(k,l),(k',l') \\ k+k' \neq 0}} (B_k \otimes B_{k'} - \tfrac{1}{2}(B_k \cdot B_{k'}) \operatorname{Id}) \nabla f_{klk'l'} e^{i\lambda_{q+1}(k+k') \cdot x} \\ II &= i\lambda_{q+1} \sum_{\substack{(k,l),(k',l') \\ k+k' \neq 0}} f_{klk'l'} (B_k \otimes B_{k'} - \tfrac{1}{2}(B_k \cdot B_{k'}) \operatorname{Id}) (k+k') e^{i\lambda_{q+1}(k+k') \cdot x}. \end{aligned}$$

Concerning II , recall that the summation is over all $l \in \mathbb{Z} \cap [0, \mu]$ and all $k \in \Lambda^e$ if l is even and all $k \in \Lambda^o$ if l is odd. Furthermore, both $\Lambda^e, \Lambda^o \subset \bar{\lambda} S^2 \cap \mathbb{Z}^3$ satisfy the conditions of Lemma 1.3. Therefore we may symmetrize the summand in II in k and k' . On the other hand, recall from Lemma 1.2 that

$$(B_k \otimes B_{k'} + B_{k'} \otimes B_k)(k+k') = (B_k \cdot B_{k'})(k+k').$$

From this we deduce that $II = 0$.

Concerning I , we first note, using the product rule, (59) and (60), that

$$[f_{klk'l'}]_N \leq C\delta_{q+1} (\lambda_q \ell^{1-N} + \|\phi_{kl} \phi_{k'l'}\|_N) \quad \text{for } N \geq 1.$$

By Lemma (62) and (54) (cf. (55)) we then conclude

$$\begin{aligned} [f_{klk'l'}]_1 &\leq C\delta_{q+1} \left(\lambda_q + \lambda_{q+1} \frac{\delta_q^{1/2} \lambda_q}{\mu} \right) \leq C\delta_{q+1} \lambda_{q+1} \frac{\delta_q^{1/2} \lambda_q}{\mu}, \\ [f_{klk'l'}]_N &\leq C\delta_{q+1} \lambda_{q+1}^{N(1-\beta)}, \quad N \geq 2. \end{aligned}$$

Applying Proposition E.1(ii) to I we obtain

$$\begin{aligned} \|R^1\|_0 &\leq \sum_{\substack{(k,l),(k',l') \\ k+k' \neq 0}} \left(\lambda_{q+1}^{\varepsilon-1} [f_{klk'l'}]_1 + \lambda_{q+1}^{-N+\varepsilon} [f_{klk'l'}]_{N+1} + \lambda_{q+1}^{-N} [f_{klk'l'}]_{N+1+\varepsilon} \right) \\ &\leq C\delta_{q+1} \left(\lambda_{q+1}^{\varepsilon} \frac{\delta_q^{1/2} \lambda_q}{\mu} + \lambda_{q+1}^{1-N\beta+\varepsilon} \right) \end{aligned} \tag{93}$$

By choosing N sufficiently large we deduce

$$\|R^1\|_0 \leq C \frac{\delta_{q+1} \delta_q^{1/2} \lambda_q \lambda_{q+1}^{\varepsilon}}{\mu}$$

as required. Moreover, differentiating we conclude $\partial_j R^1 = \mathcal{R}(\partial_j I)$ where

$$\begin{aligned} \partial_j I = & \sum_{\substack{(k,l),(k',l') \\ k+k' \neq 0}} (B_k \otimes B_{k'} - \frac{1}{2}(B_k \cdot B_{k'})\text{Id}) \cdot \\ & (i\lambda_{q+1}(k+k')_j \nabla f_{klk'l'} + \partial_j \nabla f_{klk'l'}) e^{i\lambda_{q+1}(k+k') \cdot x}. \end{aligned} \quad (94)$$

Therefore we apply again Proposition E.1(ii) to conclude the desired estimate for $\|R^1\|_1$.

Estimates on $D_t R^1$. As in the estimate for $D_t R^0$, we again make use of the identity $D_t \mathcal{R} = [v_\ell, \mathcal{R}] \nabla + \mathcal{R} D_t$ in order to write

$$\begin{aligned} D_t R^1 = & \sum_{\substack{(k,l),(k',l') \\ k+k' \neq 0}} ([v_\ell, \mathcal{R}] (\nabla U_{klk'l'} e^{i\lambda_{q+1}(k+k') \cdot x}) \\ & + i\lambda_{q+1}[v_\ell \cdot (k+k'), \mathcal{R}] (U_{klk'l'} e^{i\lambda_{q+1}(k+k') \cdot x}) + \mathcal{R} (U'_{klk'l'} e^{i\lambda_{q+1}(k+k') \cdot x})], \end{aligned}$$

where we have set $U_{klk'l'} = (B_k \otimes B_{k'} - \frac{1}{2}(B_k \cdot B_{k'})\text{Id}) \nabla f_{klk'l'}$ and

$$D_t \text{div} (w_o \otimes w_o - \sum_l \chi_l^2 \mathring{R}_{\ell,l} - \frac{|w_o|^2}{2} \text{Id}) = \sum_{\substack{(k,l),(k',l') \\ k+k' \neq 0}} U'_{klk'l'} e^{i\lambda_{q+1}(k+k') \cdot x}.$$

In order to further compute $U'_{klk'l'}$, we write

$$\begin{aligned} \nabla f_{klk'l'} e^{i\lambda_{q+1}(k+k') \cdot x} = & \chi_l \chi_{l'} (a_{kl} \nabla a_{k'l'} + a_{k'l'} \nabla a_{kl}) e^{i\lambda_{q+1}(k \cdot \Phi_l + k' \cdot \Phi_{l'})} + \\ & + i\lambda_{q+1} \chi_l \chi_{l'} a_{kl} a_{k'l'} ((D\Phi_l - \text{Id})k + (D\Phi_{l'} - \text{Id})k') e^{i\lambda_{q+1}(k \cdot \Phi_l + k' \cdot \Phi_{l'})} \end{aligned}$$

and hence, using (74),

$$\begin{aligned} D_t (\nabla f_{klk'l'} e^{i\lambda_{q+1}(k+k') \cdot x}) = & (\chi_l \chi_{l'})' (a_{kl} \nabla a_{k'l'} + a_{k'l'} \nabla a_{kl}) e^{i\lambda_{q+1}(k \cdot \Phi_l + k' \cdot \Phi_{l'})} \\ & + i\lambda_{q+1} (\chi_l \chi_{l'})' a_{kl} a_{k'l'} ((D\Phi_l - \text{Id})k + (D\Phi_{l'} - \text{Id})k') e^{i\lambda_{q+1}(k \cdot \Phi_l + k' \cdot \Phi_{l'})} \\ & - \chi_l \chi_{l'} (a_{kl} Dv_\ell^T \nabla a_{k'l'} + a_{k'l'} Dv_\ell^T \nabla a_{kl}) e^{i\lambda_{q+1}(k \cdot \Phi_l + k' \cdot \Phi_{l'})} \\ & - \chi_l \chi_{l'} a_{kl} a_{k'l'} (D\Phi_l Dv_\ell^T k + D\Phi_{l'} Dv_\ell^T k') e^{i\lambda_{q+1}(k \cdot \Phi_l + k' \cdot \Phi_{l'})} \\ =: & (\Sigma_{klk'l'}^1 + \Sigma_{klk'l'}^2 + \Sigma_{klk'l'}^3 + \Sigma_{klk'l'}^4) \phi_{kl} \phi_{k'l'} =: \Sigma_{klk'l'} \phi_{kl} \phi_{k'l'}. \end{aligned}$$

Ignoring the subscripts we can use (106), Lemma 3.1 and Lemma 3.2 to estimate

$$\|\Sigma\|_N \leq C \delta_{q+1} \lambda_q \ell^{-N} (\mu + \lambda_{q+1} \delta_q^{1/2} + \delta_q^{1/2} \lambda_q + \delta_q^{1/2}) \stackrel{(55)}{\leq} C \delta_{q+1} \lambda_{q+1} \delta_q^{1/2} \lambda_q \ell^{-N}.$$

We thus conclude

$$\begin{aligned} \|U'_{klk'l'}\|_N & \leq C \|\Sigma_{klk'l'}\|_N + C \|\Sigma_{klk'l'}\|_0 \|\phi_{kl} \phi_{k'l'}\|_N \\ & \leq C \delta_{q+1} \lambda_{q+1} \delta_q^{1/2} \lambda_q (\ell^{-N} + \lambda_{q+1}^{N(1-\beta)}) \leq C \delta_{q+1} \delta_q^{1/2} \lambda_q \lambda_{q+1}^{1+N(1-\beta)} \end{aligned}$$

The estimate on $\|D_t R^1\|_0$ now follows exactly as above for $D_t R^0$ applying Proposition F.1 to the commutator terms. This concludes the verification of (83).

Estimates on R^2 and $D_t R^2$. Using Lemma 3.1 we have

$$\begin{aligned}\|R^2\|_0 &\leq C(\|w_c\|_0^2 + \|w_o\|_0\|w_c\|_0) \leq C\delta_{q+1}\frac{\delta_q^{1/2}\lambda_q}{\mu}, \\ \|R^2\|_1 &\leq C(\|w_c\|_1\|w_c\|_0 + \|w_o\|_1\|w_c\|_0 + \|w_o\|_0\|w_c\|_1) \leq C\delta_{q+1}\frac{\delta_q^{1/2}\lambda_q}{\mu}\lambda_{q+1}.\end{aligned}$$

Similarly, with the Lemmas 3.1 and 3.2 we achieve

$$\|D_t R^2\|_0 \leq C\|D_t w_c\|_0(\|w_o\|_0 + \|w_c\|_0) + C\|D_t w_o\|_0\|w_c\|_0 \leq C\delta_{q+1}\delta_q^{1/2}\lambda_q.$$

Estimates on R^3 and $D_t R^3$. The estimates on $\|R^3\|_0$ and $\|R^3\|_1$ are a direct consequence of the mollification estimates (26) and (28) as well as Lemma 3.1. Moreover,

$$\begin{aligned}\|D_t R^3\|_0 &\leq \|v - v_\ell\|_0\|D_t w\|_0 + (\|D_t v\|_0 + \|D_t v_\ell\|_0)\|w\|_0 \\ &= \|v - v_\ell\|_0(\|D_t w_c\|_0 + \|D_t w_o\|_0) + (\|D_t v\|_0 + \|D_t v_\ell\|_0)\|w\|_0\end{aligned}\quad (95)$$

Concerning $D_t v$, note that, by our inductive hypothesis

$$\begin{aligned}\|D_t v\|_0 &\leq \|\partial_t v + v \cdot \nabla v\|_0 + \|v - v_\ell\|_0\|v\|_1 \\ &\leq \|p_q\|_1 + \|\dot{R}_q\|_1 + C\delta_q\lambda_q^2\ell \leq C\delta_q\lambda_q.\end{aligned}$$

Thus the required estimate on $D_t R^3$ follows from Lemma 3.2.

Estimates on R^4 and $D_t R^4$. From the mollification estimates (27) and (29) we deduce

$$\begin{aligned}\|R^4\|_0 &\leq C\|\dot{R}\|_1\ell \leq C\delta_{q+1}\lambda_q\ell \\ \|R^4\|_1 &\leq 2\|\dot{R}\|_1 \leq C\delta_{q+1}\lambda_q.\end{aligned}$$

As for $D_t R^4$, observe first that, using our inductive hypothesis,

$$\|D_t \dot{R}\|_0 \leq \|\partial_t \dot{R} + v \cdot \nabla \dot{R}\|_0 + \|v_\ell - v\|_0\|\dot{R}\|_1 \leq C\delta_{q+1}\delta_q^{1/2}\lambda_q + C\delta_{q+1}\delta_q^{1/2}\lambda_q^2\ell$$

Moreover,

$$\begin{aligned}D_t \dot{R}_\ell &= (D_t \dot{R}) * \psi_\ell + v_\ell \cdot \nabla \dot{R}_\ell - (v_\ell \cdot \nabla \dot{R}) * \psi_\ell \\ &= (D_t \dot{R}) * \psi_\ell + \operatorname{div} \left(v_\ell \otimes \dot{R}_\ell - (v \otimes \dot{R}) * \psi_\ell \right) + [(v - v_\ell) \cdot \nabla \dot{R}] * \psi_\ell,\end{aligned}\quad (96)$$

where we have used that $\operatorname{div} v = 0$. Using Proposition C.1 we deduce

$$\|v_\ell \otimes \dot{R}_\ell - (v \otimes \dot{R}) * \psi_\ell\|_1 \leq C\delta_{q+1}\delta_q^{1/2}\lambda_q\lambda_q\ell. \quad (97)$$

Gathering all the estimates we then achieve

$$\|D_t R^4\|_0 \leq \|D_t \dot{R}\|_0 + \|D_t \dot{R}_\ell\|_0 \leq C\delta_{q+1}\lambda_q\delta_q^{1/2}.$$

The estimate (86) follows now using (55).

Estimates on R^5 . Recall that $D_t \dot{R}_{\ell,l} = 0$. Therefore, using the arguments from (96)

$$\|D_t(\dot{R}_\ell - \dot{R}_{\ell,l})\|_0 = \|D_t \dot{R}_\ell\|_0 \leq C\delta_{q+1}\delta_q^{1/2}\lambda_q.$$

On the other hand, using again the identity (96) and Proposition C.1

$$\begin{aligned} \|D_t(\dot{R}_\ell - \dot{R}_{\ell,l})\|_1 &= \|D_t \dot{R}_\ell\|_1 \leq C\ell^{-1}\|D_t \dot{R}\|_0 + \|v_\ell \otimes \dot{R}_\ell - (v \otimes \dot{R}) * \psi_\ell\|_2 \\ &\quad + C\ell^{-1}\|v - v_\ell\|_0\|\dot{R}\|_1 \leq C\delta_{q+1}\delta_q^{1/2}\lambda_q\ell^{-1}. \end{aligned}$$

Since $\dot{R}_{\ell,l}(x, t\mu^{-1}) = \dot{R}_\ell(x, t\mu^{-1})$, the difference $\dot{R}_\ell - \dot{R}_{\ell,l}$ vanishes at $t = l\mu^{-1}$. From Proposition B.1 we deduce that, for times t in the support of χ_l (i.e. $|t - l\mu^{-1}| < \mu^{-1}$),

$$\begin{aligned} \|\dot{R}_\ell - \dot{R}_{\ell,l}\|_0 &\leq C\mu^{-1}\|D_t(\dot{R}_\ell - \dot{R}_{\ell,l})\|_0 \leq C\mu^{-1}\delta_{q+1}\delta_q^{1/2}\lambda_q \\ \|\dot{R}_\ell - \dot{R}_{\ell,l}\|_1 &\leq C\mu^{-1}\|D_t(\dot{R}_\ell - \dot{R}_{\ell,l})\|_1 \leq C\mu^{-1}\delta_{q+1}\delta_q^{1/2}\lambda_q\ell^{-1}. \end{aligned}$$

The desired estimates on $\|R^5\|_0$ and $\|R^5\|_1$ follow then easily using (55).

Estimate on $D_t R^5$. In this case we compute

$$D_t R^5 = \sum_l 2\chi_l \partial_t \chi_l (\dot{R}_\ell - \dot{R}_{\ell,l}) + \sum_l \chi_l^2 D_t \dot{R}_\ell.$$

The second summand has been estimate above and, since $\|\partial_t \chi_l\|_0 \leq C\mu$, the first summand can be estimated by $C\mu\delta_{q+1}\delta_q^{1/2}\lambda_q\mu^{-1}$ (again appealing to the arguments above).

Proof of (89). To achieve this last inequality, observe that

$$\|\partial_t \dot{R}_1 + v_1 \cdot \nabla \dot{R}_1\|_0 \leq \|D_t \dot{R}_1\|_0 + (\|v - v_\ell\|_0 + \|w\|_0) \|\dot{R}_1\|_1.$$

Hence (89) is a simple consequence of (88) and (55). \square

6. CONCLUSION OF THE PROOF

In Sections 2-5 we showed the construction for a single step, referring to (v_q, p_q, \dot{R}_q) as (v, p, \dot{R}) and to $(v_{q+1}, p_{q+1}, \dot{R}_{q+1})$ as (v_1, p_1, \dot{R}_1) . From now on we will consider the full iteration again, hence using again the indices q and $q+1$.

In order to proceed, recall that the sequences $\{\delta_q\}_{q \in \mathbb{N}}$ and $\{\lambda_q\}_{q \in \mathbb{N}}$ are chosen to satisfy

$$\delta_q = a^{-b^q}, \quad a^{cb^{q+1}} \leq \lambda_q \leq 2a^{cb^{q+1}}$$

for some given constants $c > 5/2$ and $b > 1$ and for $a > 1$. Note that this has the consequence that if a is chosen sufficiently large (depending only on $b > 1$) then

$$\delta_q^{1/2}\lambda_q^{1/5} \leq \delta_{q+1}^{1/2}\lambda_{q+1}^{1/5}, \quad \delta_{q+1} \leq \delta_q, \quad \text{and} \quad \lambda_q \leq \lambda_{q+1}^{\frac{2}{b+1}}. \quad (98)$$

6.1. Choice of the parameters μ and ℓ . We start by specifying the parameters $\mu = \mu_q$ and $\ell = \ell_q$: we determine them optimizing the right hand side of (88). More precisely, we set

$$\mu := \delta_{q+1}^{1/4} \delta_q^{1/4} \lambda_q^{1/2} \lambda_{q+1}^{1/2} \quad (99)$$

so that the first two expressions in (88) are equal, and then, having determined μ , set

$$\ell := \delta_{q+1}^{-1/8} \delta_q^{1/8} \lambda_q^{-1/4} \lambda_{q+1}^{-3/4} \quad (100)$$

so that the last two expressions in (88) are equal (up to a factor $\lambda_{q+1}^\varepsilon$).

In turn, these choices lead to

$$\begin{aligned} \|\mathring{R}_{q+1}\|_0 + \frac{1}{\lambda_{q+1}} \|\mathring{R}_{q+1}\|_1 &\leq C \delta_{q+1}^{3/4} \delta_q^{1/4} \lambda_q^{1/2} \lambda_{q+1}^{\varepsilon-1/2} + C \delta_{q+1}^{3/8} \delta_q^{5/8} \lambda_q^{3/4} \lambda_{q+1}^{\varepsilon-3/4} \\ &= C \delta_{q+1}^{3/4} \delta_q^{1/4} \lambda_q^{1/2} \lambda_{q+1}^{\varepsilon-1/2} \left(1 + \left(\frac{\delta_q^{1/2} \lambda_q^{1/3}}{\delta_{q+1}^{1/2} \lambda_{q+1}^{1/3}} \right)^{3/4} \right) \\ &\stackrel{(98)}{\leq} C \delta_{q+1}^{3/4} \delta_q^{1/4} \lambda_q^{1/2} \lambda_{q+1}^{\varepsilon-1/2}. \end{aligned} \quad (101)$$

Let us check that the conditions (54) are satisfied for some $\beta > 0$ (remember that β should be independent of q). To this end we calculate

$$\begin{aligned} \frac{\delta_q^{1/2} \lambda_q \ell}{\delta_{q+1}^{1/2}} &= \left(\frac{\delta_q^{1/2} \lambda_q^{3/5}}{\delta_{q+1}^{1/2} \lambda_{q+1}^{3/5}} \right)^{5/4}, & \frac{\delta_q^{1/2} \lambda_q}{\mu} &= \left(\frac{\delta_q^{1/2} \lambda_q}{\delta_{q+1}^{1/2} \lambda_{q+1}} \right)^{1/2}, \\ \frac{1}{\ell \lambda_{q+1}} &= \left(\frac{\delta_{q+1}^{1/2} \lambda_q}{\delta_q^{1/2} \lambda_{q+1}} \right)^{1/4}, & \frac{\mu}{\delta_q^{1/2} \lambda_{q+1}} &= \left(\frac{\delta_{q+1}^{1/2} \lambda_q}{\delta_q^{1/2} \lambda_{q+1}} \right)^{1/2}. \end{aligned}$$

Hence the conditions (54) follow from (98) choosing $\beta = \frac{b-1}{5b+5}$.

6.2. Proof of Proposition 0.2. Fix the constants $c > \frac{5}{2}$ and $b > 1$ and also an $\varepsilon > 0$ whose choice, like that of $a > 1$, will be specified later. The proposition is proved inductively. The initial triple is defined to be $(v_0, p_0, \mathring{R}_0) = (0, 0, 0)$. Given now $(v_q, p_q, \mathring{R}_q)$ satisfying the estimates (6)-(13), we claim that the triple $(v_{q+1}, p_{q+1}, \mathring{R}_{q+1})$ constructed above satisfies again all the corresponding estimates.

Estimates on \mathring{R}_{q+1} . Note first of all that, using the form of the estimates in (88) and (89), the estimates (11) and (13) follow from (10). On the other hand, in light of (101), (10) follows from the recursion relation

$$C \delta_{q+1}^{3/4} \delta_q^{1/4} \lambda_q^{1/2} \lambda_{q+1}^{\varepsilon-1/2} \leq \eta \delta_{q+2}.$$

Using our choice of δ_q and λ_q from Proposition 0.2, we see that this inequality is equivalent to

$$C \leq a^{\frac{1}{4}b^q(1+3b-2cb+(2c-4-4\varepsilon c)b^2)},$$

which, since $b > 1$, is satisfied for all $q \geq 1$ for a sufficiently large fixed constant $a > 1$, provided

$$(1 + 3b - 2cb + (2c - 4 - 4\epsilon c)b^2) > 0.$$

Factorizing, we obtain the inequality $(b - 1)((2c - 4)b - 1) - 4\epsilon cb^2 > 0$. It is then easy to see that for any $b > 1$ and $c > 5/2$ there exists $\epsilon > 0$ so that this inequality is satisfied. In this way we can choose $\epsilon > 0$ (and β above) depending solely on b and c . Consequently, this choice will determine all the constants in the estimates in Sections 2-5. We can then pick $a > 1$ sufficiently large so that (10), and hence also (11) and (13) hold for \dot{R}_{q+1} .

Estimates on $v_{q+1} - v_q$. By (45), Lemma 3.1 and (54) we conclude

$$\|v_{q+1} - v_q\|_0 \leq \|w_o\|_0 + \|w_c\|_0 \leq \delta_{q+1}^{1/2} \left(\frac{M}{2} + \lambda_{q+1}^{-\beta} \right) \quad (102)$$

$$\|v_{q+1} - v_q\|_1 \leq \|w_o\|_1 + \|w_c\|_1 \leq \delta_{q+1}^{1/2} \left(\frac{M}{2} + \lambda_{q+1}^{-\beta} \right). \quad (103)$$

Since $\lambda_{q+1} \geq \lambda_1 \geq a^{cb^2}$, for a sufficiently large we conclude (6) and (7).

Estimate on the energy. Recall Lemma 4.1 and observe that, by (54), $\frac{\delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q}{\lambda_{q+1}} \leq \frac{\delta_{q+1}^{1/2} \mu}{\lambda_{q+1}}$. Moreover,

$$\delta_{q+1} \delta_q^{1/2} \lambda_q = a^{-b^{q+1} - b^q/2 + cb^{q+1}} = a^{b^q((c-1)b - 1/2)} \geq a \geq 1.$$

So the right hand side of (75) is smaller than $C \frac{\delta_{q+1} \delta_q^{1/2} \lambda_q}{\mu} + C \frac{\delta_{q+1}^{1/2} \mu}{\lambda_{q+1}}$, i.e. smaller (up to a constant factor) than the right hand side of (88). Thus, the argument used above to prove (10) gives also (12).

Estimates on $p_{q+1} - p_1$. From the definition of p_{q+1} in (52) we deduce

$$\|p_{q+1} - p_q\|_0 \leq \frac{1}{2} (\|w_o\|_0 + \|w_c\|_0)^2 + C\ell \|v_q\|_1 \|w\|_0$$

As already argued in the estimate for (6), $\|w_o\| + \|w_c\| \leq M\delta_q^{1/2}$. Moreover $C\ell \|v_1\|_1 \|w\|_0 \leq CM\delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q \ell$, which is smaller than the right hand side of (88). Having already argued that such quantity is smaller than $\eta\delta_{q+2}$ we can obviously bound $C\ell \|v_q\|_1 \|w\|_0$ with $\frac{M^2}{2} \delta_{q+1}$. This shows (8). Moreover, differentiating (52) we achieve the bound

$$\|p_{q+1} - p_q\|_1 \leq (\|w_o\|_1 + \|w_c\|_1)(\|w_o\|_0 + \|w_c\|_0) + C\delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q \lambda_{q+1} \ell$$

and arguing as above we conclude (9).

Estimates (14). Here we can use the obvious identity $\partial_t w_q = D_t w_q - (v_q)_\ell \cdot \nabla w_q$ together with Lemmas 3.1 and 3.2 to obtain $\|\partial_t v_{q+1} - \partial_t v_q\|_0 \leq C\delta_{q+1}^{1/2} \lambda_{q+1}$. Then, using (21), we conclude $\|\partial_t v_q\|_0 \leq C\delta_q^{1/2} \lambda_q$.

To handle $\partial_t p_{q+1} - \partial_t p_q$ observe first that, by our construction,

$$\begin{aligned} \|\partial_t(p_{q+1} - p_q)\|_0 &\leq (\|w_c\|_0 + \|w_o\|_0)(\|\partial_t w_c\|_0 + \|\partial_t w_o\|_0) \\ &\quad + 2\|w\|_0\|\partial_t v_q\|_0 + \ell\|v_q\|_1\|\partial_t w\|_0. \end{aligned}$$

As above, we can derive the estimates $\|\partial_t w_o\|_0 + \|\partial_t w_c\|_0 \leq C\delta_{q+1}^{1/2}\lambda_{q+1}$ from Lemmas 3.1 and 3.2. Hence

$$\|\partial_t(p_{q+1} - p_q)\|_0 \leq C\delta_{q+1}\lambda_{q+1} + C\delta_{q+1}^{1/2}\delta_q^{1/2}\lambda_q + C\delta_q^{1/2}\lambda_q\ell\delta_{q+1}^{1/2}\lambda_{q+1}. \quad (104)$$

Since $\ell \leq \lambda_q^{-1}$ and $\delta_q^{1/2}\lambda_q \leq \delta_{q+1}^{1/2}\lambda_{q+1}$, the desired inequality follows. This concludes the proof.

APPENDIX A. HÖLDER SPACES

In the following $m = 0, 1, 2, \dots$, $\alpha \in (0, 1)$, and β is a multi-index. We introduce the usual (spatial) Hölder norms as follows. First of all, the supremum norm is denoted by $\|f\|_0 := \sup_{\mathbb{T}^3 \times [0,1]} |f|$. We define the Hölder seminorms as

$$\begin{aligned} [f]_m &= \max_{|\beta|=m} \|D^\beta f\|_0, \\ [f]_{m+\alpha} &= \max_{|\beta|=m} \sup_{x \neq y, t} \frac{|D^\beta f(x, t) - D^\beta f(y, t)|}{|x - y|^\alpha}, \end{aligned}$$

where D^β are *space derivatives* only. The Hölder norms are then given by

$$\begin{aligned} \|f\|_m &= \sum_{j=0}^m [f]_j \\ \|f\|_{m+\alpha} &= \|f\|_m + [f]_{m+\alpha}. \end{aligned}$$

Moreover, we will write $[f(t)]_\alpha$ and $\|f(t)\|_\alpha$ when the time t is fixed and the norms are computed for the restriction of f to the t -time slice.

Recall the following elementary inequalities:

$$[f]_s \leq C(\varepsilon^{r-s}[f]_r + \varepsilon^{-s}\|f\|_0) \quad (105)$$

for $r \geq s \geq 0$, $\varepsilon > 0$, and

$$[fg]_r \leq C([f]_r\|g\|_0 + \|f\|_0[g]_r) \quad (106)$$

for any $1 \geq r \geq 0$. From (105) with $\varepsilon = \|f\|_0^{\frac{1}{r}}[f]_r^{-\frac{1}{r}}$ we obtain the standard interpolation inequalities

$$[f]_s \leq C\|f\|_0^{1-\frac{s}{r}}[f]_r^{\frac{s}{r}}. \quad (107)$$

Next we collect two classical estimates on the Hölder norms of compositions. These are also standard, for instance in applications of the Nash-Moser iteration technique.

Proposition A.1. *Let $\Psi : \Omega \rightarrow \mathbb{R}$ and $u : \mathbb{R}^n \rightarrow \Omega$ be two smooth functions, with $\Omega \subset \mathbb{R}^N$. Then, for every $m \in \mathbb{N} \setminus \{0\}$ there is a constant C (depending only on m , N and n) such that*

$$[\Psi \circ u]_m \leq C([\Psi]_1[u]_m + [\Psi]_m \|u\|_0^{m-1} [u]_m) \quad (108)$$

$$[\Psi \circ u]_m \leq C([\Psi]_1[u]_m + [\Psi]_m [u]_1^m). \quad (109)$$

APPENDIX B. ESTIMATES FOR TRANSPORT EQUATIONS

In this section we recall some well known results regarding smooth solutions of the *transport equation*:

$$\begin{cases} \partial_t f + v \cdot \nabla f = g, \\ f|_{t_0} = f_0, \end{cases} \quad (110)$$

where $v = v(t, x)$ is a given smooth vector field. We denote the material derivative $\partial_t + v \cdot \nabla$ by D_t . We will consider solutions on the entire space \mathbb{R}^3 and treat solutions on the torus simply as periodic solution in \mathbb{R}^3 .

Proposition B.1. *Any solution f of (110) satisfies*

$$\|f(t)\|_0 \leq \|f_0\|_0 + \int_{t_0}^t \|g(\tau)\|_0 d\tau, \quad (111)$$

$$[f(t)]_1 \leq [f_0]_1 e^{(t-t_0)[v]_1} + \int_{t_0}^t e^{(t-\tau)[v]_1} [g(\tau)]_1 d\tau, \quad (112)$$

and, more generally, for any $N \geq 2$ there exists a constant $C = C_N$ so that

$$\begin{aligned} [f(t)]_N &\leq ([f_0]_N + C(t-t_0)[v]_N[f_0]_1) e^{C(t-t_0)[v]_1} + \\ &+ \int_{t_0}^t e^{C(t-\tau)[v]_1} ([g(\tau)]_N + [v]_N[g(\tau)]_1) d\tau. \end{aligned} \quad (113)$$

Define $\Phi(t, \cdot)$ to be the inverse of the flux X of v starting at time t_0 as the identity (i.e. $\frac{d}{dt}X = v(X, t)$ and $X(x, t_0) = x$). Under the same assumptions as above:

$$\|D\Phi(t) - \text{Id}\|_0 \leq e^{(t-t_0)[v]_1} - 1, \quad (114)$$

$$[\Phi(t)]_N \leq C(t-t_0)[v]_N e^{C(t-t_0)[v]_1} \quad \forall N \geq 2. \quad (115)$$

Proof. We start with the following elementary observation for transport equations: if f solves (110), then $\frac{d}{dt}f(X(t, x), t) = g(X(t, x), t)$ and consequently

$$f(t, x) = f_0(\Phi(x, t)) + \int_{t_0}^t g(X(\Phi(t, x), \tau), \tau) d\tau.$$

The maximum principle (111) follows immediately. Next, differentiate (110) in x to obtain the identity

$$D_t Df = (\partial_t + v \cdot \nabla) Df = Dg - Df Dv.$$

Applying (111) to Df yields

$$[f(t)]_1 \leq [f_0]_1 + \int_{t_0}^t ([g(\tau)]_1 + [v]_1[f(\tau)]_1) d\tau.$$

An application of Gronwall's inequality then yields (112).

More generally, differentiating (110) N times yields

$$\partial_t D^N f + (v \cdot \nabla) D^N f = D^N g + \sum_{j=0}^{N-1} c_{j,N} D^{j+1} f : D^{N-j} v \quad (116)$$

(where $:$ is a shorthand notation for sums of products of entries of the corresponding tensors).

Also, using (111) and the interpolation inequality (107) we can estimate

$$[f(t)]_N \leq [f_0]_N + \int_{t_0}^t ([g(\tau)]_N + C([v]_N[f(\tau)]_1 + [v]_1[f(\tau)]_N)) d\tau.$$

Plugging now the estimate (112), Gronwall's inequality leads – after some elementary calculations – to (113).

The estimate (115) follows easily from (113) observing that Φ solves (110) with $g = 0$ and $D^2\Phi(\cdot, t_0) = 0$. Consider next $\Psi(x, t) = \Phi(x, t) - x$ and observe first that $\partial_t \Psi + v \cdot \nabla \Psi = -v$. Since $D\Psi(\cdot, t_0) = 0$, we apply (112) to conclude

$$[\Psi(t)]_1 \leq \int_{t_0}^t e^{(t-\tau)[v]_1} [v]_1 d\tau = e^{(t-t_0)[v]_1} - 1.$$

Since $D\Psi(x, t) = D\Phi(x, t) - \text{Id}$, (114) follows. \square

APPENDIX C. CONSTANTIN-E-TITI COMMUTATOR ESTIMATE

Finally, we recall the quadratic commutator estimate from [2] (cf. also with [3, Lemma 1]):

Proposition C.1. *Let $f, g \in C^\infty(\mathbb{T}^3 \times \mathbb{T})$ and ψ the mollifier of Section 2. For any $r \geq 0$ we have the estimate*

$$\left\| (f * \chi_\ell)(g * \chi_\ell) - (fg) * \chi_\ell \right\|_r \leq C \ell^{2-r} \|f\|_1 \|g\|_1,$$

where the constant C depends only on r .

APPENDIX D. SCHAUDER ESTIMATES

We recall here the following consequences of the classical Schauder estimates (cf. [10, Proposition 5.1]).

Proposition D.1. *For any $\alpha \in (0, 1)$ and any $m \in \mathbb{N}$ there exists a constant $C(\alpha, m)$ with the following properties. If $\phi, \psi : \mathbb{T}^3 \rightarrow \mathbb{R}$ are the unique solutions of*

$$\begin{cases} \Delta \phi = f \\ f \phi = 0 \end{cases} \quad \begin{cases} \Delta \psi = \text{div } F \\ f \psi = 0 \end{cases},$$

then

$$\|\phi\|_{m+2+\alpha} \leq C(m, \alpha) \|f\|_{m, \alpha} \quad \text{and} \quad \|\psi\|_{m+1+\alpha} \leq C(m, \alpha) \|F\|_{m, \alpha}. \quad (117)$$

Moreover we have the estimates

$$\|\mathcal{R}v\|_{m+1+\alpha} \leq C(m, \alpha) \|v\|_{m+\alpha} \quad (118)$$

$$\|\mathcal{R}(\operatorname{div} A)\|_{m+\alpha} \leq C(m, \alpha) \|A\|_{m+\alpha} \quad (119)$$

APPENDIX E. STATIONARY PHASE LEMMA

We recall here the following simple facts (for a proof we refer to [10])

Proposition E.1. (i) Let $k \in \mathbb{Z}^3 \setminus \{0\}$ and $\lambda \geq 1$ be fixed. For any $a \in C^\infty(\mathbb{T}^3)$ and $m \in \mathbb{N}$ we have

$$\left| \int_{\mathbb{T}^3} a(x) e^{i\lambda k \cdot x} dx \right| \leq \frac{[a]_m}{\lambda^m}. \quad (120)$$

(ii) Let $k \in \mathbb{Z}^3 \setminus \{0\}$ be fixed. For a smooth vector field $a \in C^\infty(\mathbb{T}^3; \mathbb{R}^3)$ let $F(x) := a(x) e^{i\lambda k \cdot x}$. Then we have

$$\|\mathcal{R}(F)\|_\alpha \leq \frac{C}{\lambda^{1-\alpha}} \|a\|_0 + \frac{C}{\lambda^{m-\alpha}} [a]_m + \frac{C}{\lambda^m} [a]_{m+\alpha},$$

where $C = C(\alpha, m)$.

APPENDIX F. ONE FURTHER COMMUTATOR ESTIMATE

Proposition F.1. Let $k \in \mathbb{Z}^3 \setminus \{0\}$ be fixed. For any smooth vector field $a \in C^\infty(\mathbb{T}^3; \mathbb{R}^3)$ and any smooth function b , if we set $F(x) := a(x) e^{i\lambda k \cdot x}$, we then have

$$\begin{aligned} \|[b, \mathcal{R}](F)\|_\alpha &\leq \frac{C}{\lambda^{2-\alpha}} \|a\|_0 \|b\|_1 + \frac{C}{\lambda^{m-\alpha}} (\|a\|_m \|b\|_2 + \|a\|_2 \|b\|_m) \\ &+ \frac{C}{\lambda^m} (\|a\|_{m+\alpha} \|b\|_{2+\alpha} + \|a\|_{2+\alpha} \|b\|_{m+\alpha}), \end{aligned} \quad (121)$$

where $C = C(\alpha, m)$.

Proof. Step 1 First of all, given a vector field v define the operator

$$\mathcal{S}(v) := \nabla v + (\nabla v)^t - \frac{2}{3} (\operatorname{div} v) \operatorname{Id}.$$

First observe that

$$\operatorname{div} \mathcal{S}(v) = 0 \quad \Longleftrightarrow \quad v \equiv \text{const.} \quad (122)$$

One implication is obvious. Next, assume $\operatorname{div} \mathcal{S}(v) = 0$. This is equivalent to the equations

$$\Delta v_j + \frac{1}{3} \partial_j \operatorname{div} v = 0 \quad (123)$$

Differentiating and summing in j we then conclude

$$\frac{4}{3} \Delta \operatorname{div} v = 0.$$

Thus $\operatorname{div} v$ must be constant and, since any divergence has average zero, we conclude that $\operatorname{div} v = 0$. Thus (123) implies that $\Delta v_i = 0$ for every i , which in turn gives the desired conclusion.

From this observation we conclude the identity

$$\mathcal{R}(v) = \mathcal{S}(v) + \mathcal{R}(v - \operatorname{div} \mathcal{S}(v)) \quad \text{for all } v \in C^\infty(\mathbb{T}^3, \mathbb{R}^3). \quad (124)$$

Indeed, observe first that $\mathcal{R}(v) = \mathcal{S}(w)$, where $w = \frac{1}{4}\mathcal{P}(v) + \frac{3}{4}v$. Thus, applying the argument above, since both sides of (124) have zero averages, it suffices to show that they have the same divergence. But since $\operatorname{div} \mathcal{R}(v) = v - \mathcal{F}v$, applying the divergence we obtain

$$v - \mathcal{F}v = \operatorname{div} \mathcal{S}(v) + v - \mathcal{F}v - \operatorname{div} \mathcal{S}(v),$$

which is obviously true.

Step 2 Next, for $a \in C^\infty(\mathbb{T}^3, \mathbb{R}^3)$, $k \in \mathbb{Z}^3 \setminus \{0\}$ and $\lambda \in \mathbb{N} \setminus \{0\}$, consider

$$\mathcal{S}(ae^{i\lambda k \cdot x}) := -\mathcal{S}\left(\frac{3}{4}\frac{a}{\lambda^2|k|^2}e^{i\lambda k \cdot x} + \frac{1}{4\lambda^2|k|^2}\left(a - \frac{(a \cdot k)k}{|k|^2}\right)e^{i\lambda k \cdot x}\right).$$

Observe that

$$\mathcal{S}(bae^{i\lambda k \cdot x}) - b\mathcal{S}(ae^{i\lambda k \cdot x}) = \frac{aA(b)}{\lambda^2}e^{i\lambda k \cdot x}, \quad (125)$$

where A is an homogeneous differential operator of order one with constant coefficients (all depending only on k). Moreover,

$$ae^{i\lambda k \cdot x} - \operatorname{div} \mathcal{S}(ae^{i\lambda k \cdot x}) = \frac{B_1(a)}{\lambda}e^{i\lambda k \cdot x} + \frac{B_2(a)}{\lambda^2}e^{i\lambda k \cdot x},$$

where B_1 and B_2 are homogeneous differential operators of order 1 and 2 (respectively) with constant coefficients (again all depending only on k).

We use then the identity (124) to write

$$\begin{aligned} -[b, \mathcal{R}](F) &= \mathcal{R}(bF) - b\mathcal{R}(F) = \mathcal{S}(bae^{i\lambda k \cdot x}) - b\mathcal{S}(ae^{i\lambda k \cdot x}) \\ &\quad + \mathcal{R}\left(bF - \operatorname{div} \mathcal{S}(bae^{i\lambda k \cdot x})\right) - b\mathcal{R}\left(F - \operatorname{div} \mathcal{S}(ae^{i\lambda k \cdot x})\right) \\ &= \frac{aA(b)}{\lambda^2}e^{i\lambda k \cdot x} + \mathcal{R}\left(\frac{B_1(ab)}{\lambda}e^{i\lambda k \cdot x} + \frac{B_2(ab)}{\lambda^2}e^{i\lambda k \cdot x}\right) \\ &\quad - b\mathcal{R}\left(\frac{B_1(a)}{\lambda}e^{i\lambda k \cdot x} + \frac{B_2(a)}{\lambda^2}e^{i\lambda k \cdot x}\right). \end{aligned} \quad (126)$$

Using the Leibniz rule we can write $B_1(ab) = B_1(a)b + aB_1(b)$ and $B_2(ab) = B_2(a)b + aB_2(b) + C_1(a)C_1(b)$, where C_1 is an homogeneous operator of order

1. We can then reorder all terms to write

$$\begin{aligned} -[b, \mathcal{R}](F) &= \frac{aA(b)}{\lambda^2} e^{i\lambda k \cdot x} \\ &\quad + \mathcal{R} \left(\frac{aB_1(b)}{\lambda} e^{i\lambda k \cdot x} \right) + \mathcal{R} \left(\frac{aB_2(b) + C_1(a)C_1(b)}{\lambda^2} e^{i\lambda k \cdot x} \right) \\ &\quad - \frac{1}{\lambda} [b, \mathcal{R}] \left((B_1(a)) e^{i\lambda k \cdot x} \right) - \frac{1}{\lambda^2} [b, \mathcal{R}] \left((B_2(a)) e^{i\lambda k \cdot x} \right). \end{aligned} \quad (127)$$

In the first two summands appear only derivatives of b , but there are no zero order terms in b . We can then estimate the two terms in the second line applying Proposition E.1, with $m = N - 1$ to the first summand and with $m = N - 2$ to the second summand. Applying in addition interpolation identities, we conclude

$$\begin{aligned} \|[b, \mathcal{R}](F)\|_\alpha &\leq C \frac{\|a\|_0 \|b\|_1}{\lambda^{2-\alpha}} + C \frac{\|a\|_2 \|b\|_N + \|a\|_N \|b\|_2}{\lambda^{N-\alpha}} \\ &\quad + C \frac{\|a\|_{2+\alpha} \|b\|_{N+\alpha} + \|a\|_{N+\alpha} \|b\|_{2+\alpha}}{\lambda^N} \\ &\quad + \frac{1}{\lambda} \underbrace{\left\| [b, \mathcal{R}] \left((B_1(a)) e^{i\lambda k \cdot x} \right) \right\|_\alpha}_{II} + \frac{1}{\lambda^2} \left\| [b, \mathcal{R}] \left((B_2(a)) e^{i\lambda k \cdot x} \right) \right\|_\alpha. \end{aligned} \quad (128)$$

(Indeed the above estimate is sub-optimal as we get, for instance, terms of type $\|a\|_0 \|b\|_N + \|a\|_1 \|b\|_{N-1} + \|a\|_2 \|b\|_{N-2}$ instead of $\|a\|_2 \|b\|_N$; however, this crude estimate is still sufficient for our purposes.)

Step 3 We can now apply the same idea to the term II in (128) to reach the estimate

$$\begin{aligned} \|[b, \mathcal{R}](F)\|_\alpha &\leq C \frac{\|a\|_0 \|b\|_1}{\lambda^{2-\alpha}} + C \frac{\|a\|_2 \|b\|_N + \|a\|_N \|b\|_2}{\lambda^{N-\alpha}} \\ &\quad + C \frac{\|a\|_{2+\alpha} \|b\|_{N+\alpha} + \|a\|_{N+\alpha} \|b\|_{2+\alpha}}{\lambda^N} + \frac{1}{\lambda^2} \left\| [b, \mathcal{R}] \left((B'_2(a)) e^{i\lambda k \cdot x} \right) \right\|_\alpha. \end{aligned}$$

where $B'_2 = B_2 + B_1 \circ B_1$ is second order and this time we have applied Proposition E.1 with $m = N - 2$ and $m = N - 3$ to handle the corresponding two terms of order λ^{-2} and λ^{-3} arising from II . Proceeding now inductively, we end up with

$$\begin{aligned} \|\mathcal{R}(bF) - b\mathcal{R}(F)\|_0 &\leq \frac{\|a\|_0 \|b\|_1}{\lambda^2} + C \frac{\|a\|_2 \|b\|_N + \|a\|_N \|b\|_2}{\lambda^{N-\alpha}} \\ &\quad + C \frac{\|a\|_{2+\alpha} \|b\|_{N+\alpha} + \|a\|_{N+\alpha} \|b\|_{2+\alpha}}{\lambda^N} \\ &\quad + \frac{1}{\lambda^N} \left\| \mathcal{R} \left((B'_N(a)) e^{i\lambda k \cdot x} \right) - b\mathcal{R} \left((B'_N(a)) e^{i\lambda k \cdot x} \right) \right\|_\alpha. \end{aligned} \quad (129)$$

Finally, applying Proposition D.1 to the final term we reach the desired estimate. \square

REFERENCES

- [1] CHESKIDOV, A., CONSTANTIN, P., FRIEDLANDER, S., AND SHVYDKOY, R. Energy conservation and Onsager's conjecture for the Euler equations. *Nonlinearity* 21, 6 (2008), 1233–1252.
- [2] CONSTANTIN, P., E, W., AND TITI, E. S. Onsager's conjecture on the energy conservation for solutions of Euler's equation. *Comm. Math. Phys.* 165, 1 (1994), 207–209.
- [3] CONTI, S., DE LELLIS, C., AND SZÉKELYHIDI, JR., L. h -principle and rigidity for $C^{1,\alpha}$ isometric embeddings. In *Nonlinear Partial Differential Equations*, vol. 7 of *Abel Symposia*. Springer, 2012, pp. 83–116.
- [4] COURANT, R., FRIEDRICHS, K., AND LEWY, H. On the partial difference equations of mathematical physics. *IBM J. Res. Develop.* 11 (1967), 215–234.
- [5] DANERI, S. Cauchy problem for dissipative Hölder solutions to the incompressible Euler equations. *Preprint*. (2013), 1–33.
- [6] DE LELLIS, C., AND SZÉKELYHIDI, JR., L. The Euler equations as a differential inclusion. *Ann. of Math. (2)* 170, 3 (2009), 1417–1436.
- [7] DE LELLIS, C., AND SZÉKELYHIDI, JR., L. On admissibility criteria for weak solutions of the Euler equations. *Arch. Ration. Mech. Anal.* 195, 1 (2010), 225–260.
- [8] DE LELLIS, C., AND SZÉKELYHIDI, JR., L. Dissipative Euler flows and Onsager's conjecture. *Preprint*. (2012), 1–40.
- [9] DE LELLIS, C., AND SZÉKELYHIDI, JR., L. The h -principle and the equations of fluid dynamics. *Bull. Amer. Math. Soc. (N.S.)* 49, 3 (2012), 347–375.
- [10] DE LELLIS, C., AND SZÉKELYHIDI, JR., L. Continuous dissipative Euler flows. *To appear in Inventiones* (2013), 1–26.
- [11] DUCHON, J., AND ROBERT, R. Inertial energy dissipation for weak solutions of incompressible Euler and Navier-Stokes equations. *Nonlinearity* 13, 1 (2000), 249–255.
- [12] EYINK, G. L. Energy dissipation without viscosity in ideal hydrodynamics. I. Fourier analysis and local energy transfer. *Phys. D* 78, 3-4 (1994), 222–240.
- [13] EYINK, G. L., AND SREENIVASAN, K. R. Onsager and the theory of hydrodynamic turbulence. *Rev. Modern Phys.* 78, 1 (2006), 87–135.
- [14] FRISCH, U. *Turbulence*. Cambridge University Press, Cambridge, 1995. The legacy of A. N. Kolmogorov.
- [15] ISETT, P. Hölder continuous Euler flows in three dimensions with compact support in time. *Preprint* (2012), 1–173.
- [16] KOLMOGOROV, A. N. The local structure of turbulence in incompressible viscous fluid for very large Reynolds numbers. *Proc. Roy. Soc. London Ser. A* 434, 1890 (1991), 9–13. Translated from the Russian by V. Levin, Turbulence and stochastic processes: Kolmogorov's ideas 50 years on.
- [17] ONSAGER, L. Statistical hydrodynamics. *Nuovo Cimento (9)* 6, Supplemento, 2 (Convegno Internazionale di Meccanica Statistica) (1949), 279–287.
- [18] ROBERT, R. Statistical hydrodynamics (Onsager revisited). In *Handbook of mathematical fluid dynamics, Vol. II*. North-Holland, Amsterdam, 2003, pp. 1–54.
- [19] SCHEFFER, V. An inviscid flow with compact support in space-time. *J. Geom. Anal.* 3, 4 (1993), 343–401.
- [20] SHNIRELMAN, A. Weak solutions with decreasing energy of incompressible Euler equations. *Comm. Math. Phys.* 210, 3 (2000), 541–603.

INSTITUT FÜR MATHEMATIK, UNIVERSITÄT LEIPZIG, D-04103 LEIPZIG
E-mail address: `tristan.buckmaster@math.uni-leipzig.de`

INSTITUT FÜR MATHEMATIK, UNIVERSITÄT ZÜRICH, CH-8057 ZÜRICH
E-mail address: `camillo.delellis@math.unizh.ch`

INSTITUT FÜR MATHEMATIK, UNIVERSITÄT LEIPZIG, D-04103 LEIPZIG
E-mail address: `laszlo.szekelyhidi@math.uni-leipzig.de`